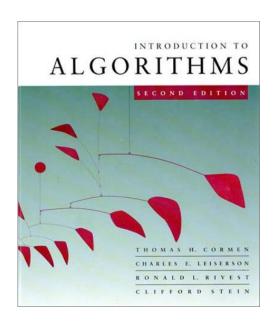


### **CS 5633 -- Spring 2008**



### More on Shortest Paths

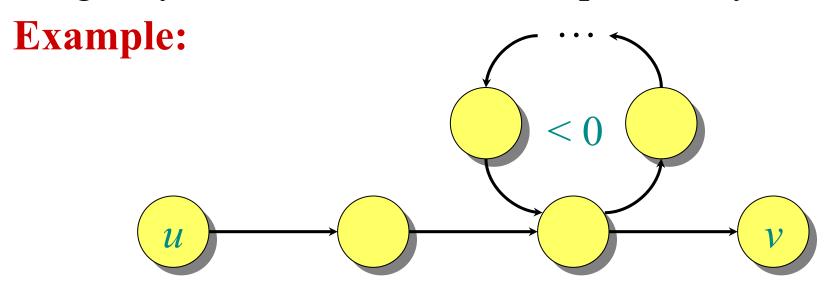
#### Carola Wenk

Slides courtesy of Charles Leiserson with small changes by Carola Wenk



# Negative-weight cycles

**Recall:** If a graph G = (V, E) contains a negative-weight cycle, then some shortest paths may not exist.



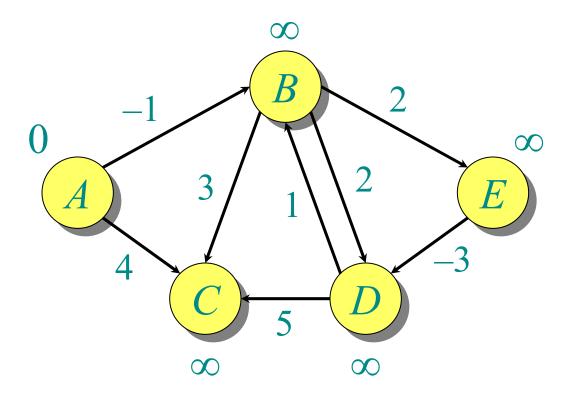
**Bellman-Ford algorithm:** Finds all shortest-path weights from a **source**  $s \in V$  to all  $v \in V$  or determines that a negative-weight cycle exists.



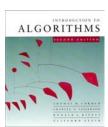
# Bellman-Ford algorithm

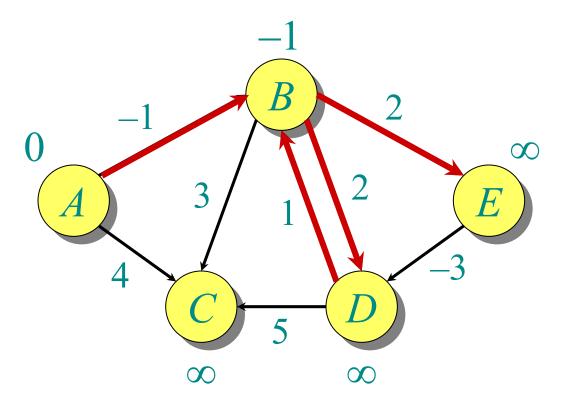
```
for i \leftarrow 1 to |V| - 1 do
  for each edge (u, v) \in E do
    if d[v] > d[u] + w(u, v) then
d[v] \leftarrow d[u] + w(u, v)
step
           \pi[v] \leftarrow u
for each edge (u, v) \in E
   do if d[v] > d[u] + w(u, v)
          then report that a negative-weight cycle exists
At the end, d[v] = \delta(s, v). Time = O(|V||E|).
```





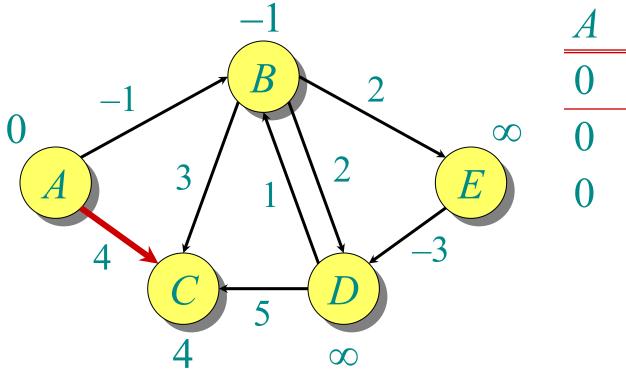
| $\boldsymbol{A}$ | $\boldsymbol{B}$ | $\boldsymbol{C}$ | D        | $\boldsymbol{E}$ |
|------------------|------------------|------------------|----------|------------------|
| 0                | $\infty$         | $\infty$         | $\infty$ | $\infty$         |





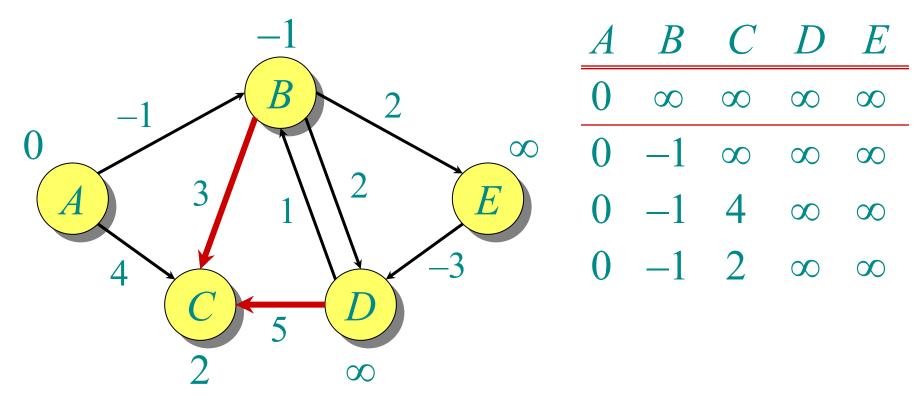
| A | B        | $\boldsymbol{C}$ | D        | $\boldsymbol{E}$ |
|---|----------|------------------|----------|------------------|
| 0 | $\infty$ | $\infty$         | $\infty$ | $\infty$         |
| 0 | _1       | $\infty$         | $\infty$ | 00               |



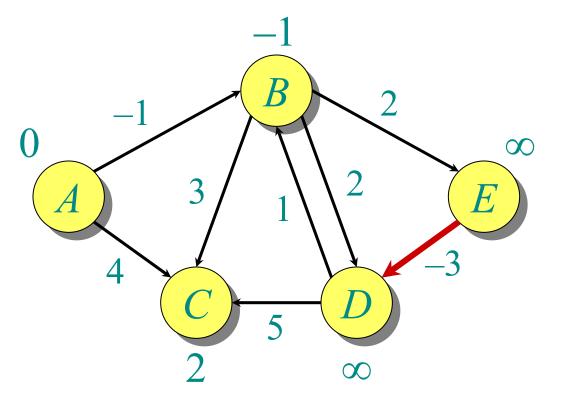


| B        | C        | D                               | $\boldsymbol{E}$   |
|----------|----------|---------------------------------|--|
| $\infty$ | $\infty$ | $\infty$                        | $\infty$   |
| -1       | $\infty$ | $\infty$                        | $\infty$   |
| -1       | 4        | $\infty$                        | $\infty$   |
|          | ∞<br>-1  | $\infty$ $\infty$ $-1$ $\infty$ | $\begin{array}{c cccc} B & C & D \\ \hline \infty & \infty & \infty \\ \hline -1 & \infty & \infty \\ -1 & 4 & \infty \end{array}$ |



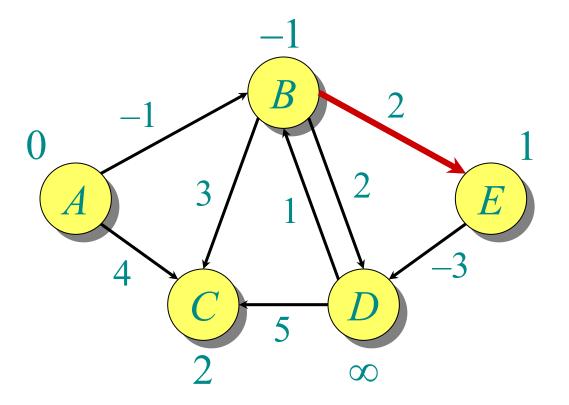






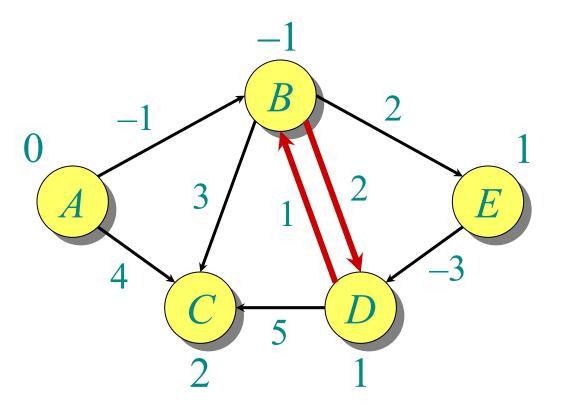
| $\boldsymbol{A}$ | B        | $\boldsymbol{C}$ | D        | E        |
|------------------|----------|------------------|----------|----------|
| 0                | $\infty$ | $\infty$         | $\infty$ | $\infty$ |
| 0                | -1       | $\infty$         | $\infty$ | $\infty$ |
| 0                | -1       | 4                | $\infty$ | $\infty$ |
| 0                | -1       | 2                | $\infty$ | $\infty$ |



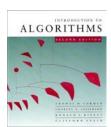


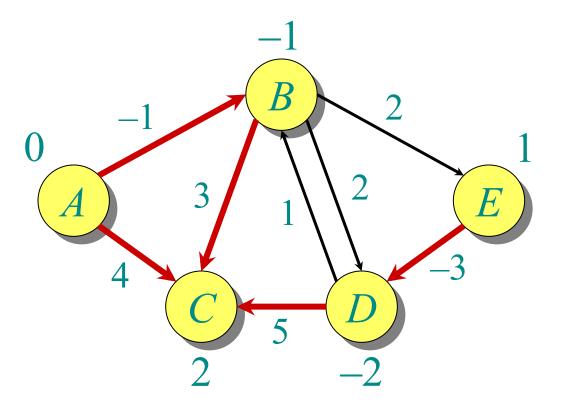
| A | B        | $\boldsymbol{C}$ | D        | E        |
|---|----------|------------------|----------|----------|
| 0 | $\infty$ | $\infty$         | $\infty$ | $\infty$ |
| 0 | -1       | $\infty$         | $\infty$ | $\infty$ |
| 0 | -1       | 4                | $\infty$ | $\infty$ |
| 0 | -1       | 2                | $\infty$ | $\infty$ |
| 0 | -1       | 2                | $\infty$ | 1        |
|   |          |                  |          |          |



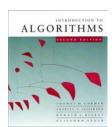


| $\boldsymbol{A}$ | B        | $\boldsymbol{C}$ | D        | E        |
|------------------|----------|------------------|----------|----------|
| 0                | $\infty$ | $\infty$         | $\infty$ | $\infty$ |
| 0                | -1       | $\infty$         | $\infty$ | $\infty$ |
| 0                | -1       | 4                | $\infty$ | $\infty$ |
| 0                | -1       | 2                | $\infty$ | 00       |
| 0                | -1       | 2                | $\infty$ | 1        |
| 0                | -1       | 2                | 1        | 1        |

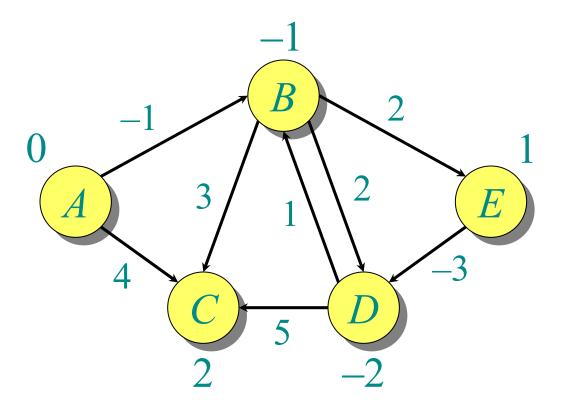




| A | В        | $\boldsymbol{C}$ | D         | E        |
|---|----------|------------------|-----------|----------|
| 0 | $\infty$ | $\infty$         | $\infty$  | $\infty$ |
| 0 | -1       | $\infty$         | $\infty$  | $\infty$ |
| 0 | -1       | 4                | $\infty$  | 00       |
| 0 | -1       | 2                | $\infty$  | 00       |
| 0 | -1       | 2                | $\infty$  | 1        |
| 0 | -1       | 2                | 1         | 1        |
| 0 | -1       | 2                | <b>-2</b> | 1        |



Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



**Note:** Values decrease monotonically.

| A | В         | $\boldsymbol{C}$ | D        | E        |
|---|-----------|------------------|----------|----------|
| 0 | $\infty$  | $\infty$         | $\infty$ | $\infty$ |
| 0 | -1        | $\infty$         | $\infty$ | $\infty$ |
| 0 | <b>-1</b> | 4                | $\infty$ | $\infty$ |
| 0 | -1        | 2                | $\infty$ | $\infty$ |
| 0 | -1        | 2                | $\infty$ | 1        |
| 0 | <b>-1</b> | 2                | 1        | 1        |
| 0 | -1        | 2                | -2       | 1        |
|   | 1 0       |                  | • ,      |          |

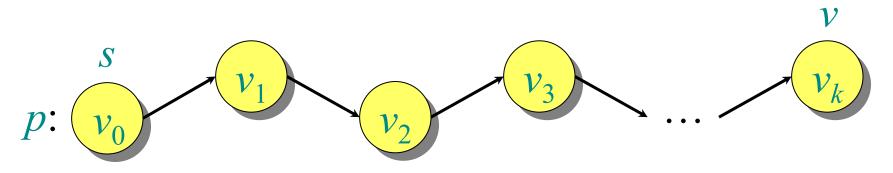
... and 2 more iterations



### **Correctness**

**Theorem.** If G = (V, E) contains no negative-weight cycles, then after the Bellman-Ford algorithm executes,  $d[v] = \delta(s, v)$  for all  $v \in V$ .

*Proof.* Let  $v \in V$  be any vertex, and consider a shortest path p from s to v with the minimum number of edges.

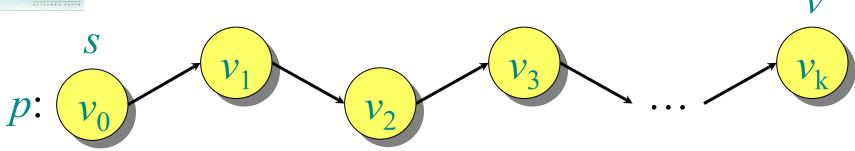


Since p is a shortest path, we have

$$\delta(s, v_i) = \delta(s, v_{i-1}) + w(v_{i-1}, v_i).$$



# **Correctness (continued)**



Initially,  $d[v_0] = 0 = \delta(s, v_0)$ , and d[s] is unchanged by subsequent relaxations.

- After 1 pass through E, we have  $d[v_1] = \delta(s, v_1)$ .
- After 2 passes through E, we have  $d[v_2] = \delta(s, v_2)$ .

• • •

• After k passes through E, we have  $d[v_k] = \delta(s, v_k)$ . Since G contains no negative-weight cycles, p is simple. Longest simple path has  $\leq |V| - 1$  edges.



# Detection of negative-weight cycles

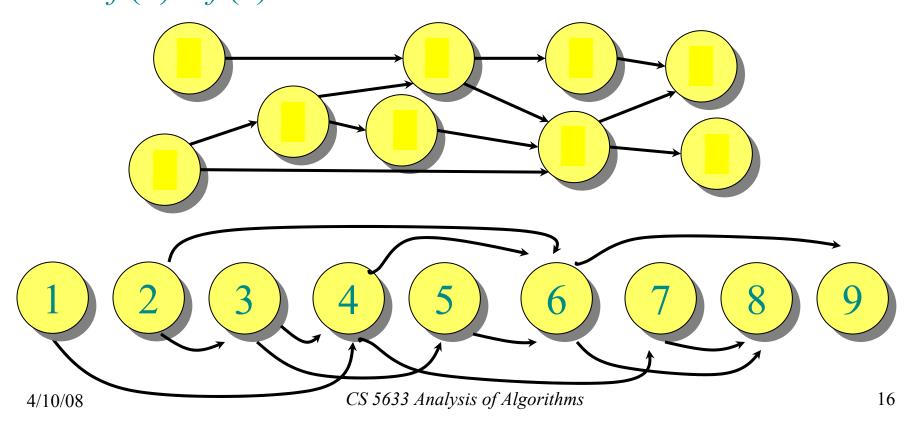
**Corollary.** If a value d[v] fails to converge after |V| - 1 passes, there exists a negative-weight cycle in G reachable from S.



# DAG shortest paths

If the graph is a *directed acyclic graph* (*DAG*), we first *topologically sort* the vertices.

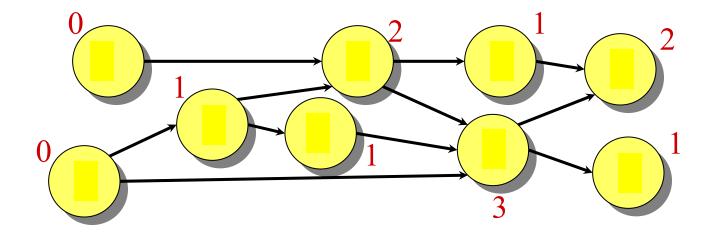
• Determine  $f: V \to \{1, 2, ..., |V|\}$  such that  $(u, v) \in E$  $\Rightarrow f(u) < f(v)$ .





# **Topological Sort Algorithm**

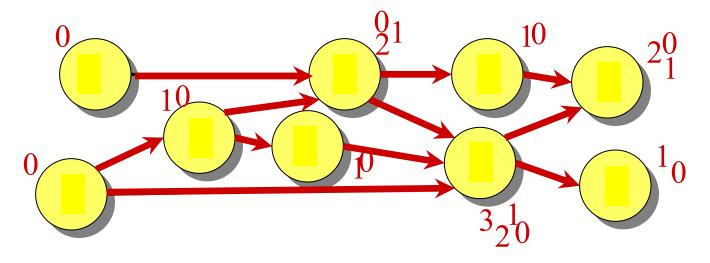
- Store vertices in a priority min-queue, with the in-degree of the vertex as the key
- While queue is not empty
  - Extract minimum vertex v, and give it next number
  - Decrease keys of all adjacent vertices by 1





# **Topological Sort Algorithm**

- Store vertices in a priority min-queue, with the in-degree of the vertex as the key
- While queue is not empty
  - Extract minimum vertex v, and give it next number
  - Decrease keys of all adjacent vertices by 1





# **Topological Sort Algorithm**

#### **Runtime:**

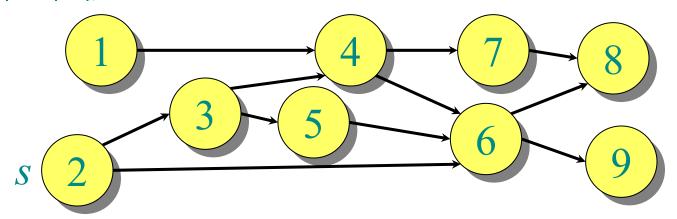
- O(|V|) to build heap + O(|E|) DECREASE-KEY ops
- $\Rightarrow$  O(|V| + |E| log |V|) with a binary heap
- $\Rightarrow$  O(|V| + |E|) with a Fibonacci heap
- Order the vertices according to decreasing finishing times as calculated by DFS (Correctness proof see book)
- $\Rightarrow$  O(|V| + |E|)



# DAG shortest paths

If the graph is a *directed acyclic graph* (*DAG*), we first *topologically sort* the vertices.

- Determine  $f: V \to \{1, 2, ..., |V|\}$  such that  $(u, v) \in E$  $\Rightarrow f(u) < f(v)$ .
- O(|V| + |E|) time



• Walk through the vertices  $u \in V$  in this order, relaxing the edges in Adj[u], thereby obtaining the shortest paths from s in a total of O(|V| + |E|) time.



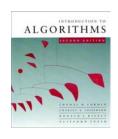
## Shortest paths

#### Single-source shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| \log |V|)$
- General: Bellman-Ford: O(|V||E|)
- DAG: One pass of Bellman-Ford: O(|V| + |E|)

#### All-pairs shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm |V| times:  $O(|V||E| \log |V|)$
- General
  - Bellman-Ford |V| times:  $O(|V|^2|E|)$
  - Floyd-Warshall:  $O(|V|^3)$



## All-pairs shortest paths

**Input:** Digraph G = (V, E), where |V| = n, with edge-weight function  $w : E \to \mathbb{R}$ .

Output:  $n \times n$  matrix of shortest-path lengths  $\delta(i, j)$  for all  $i, j \in V$ .

#### Algorithm #1:

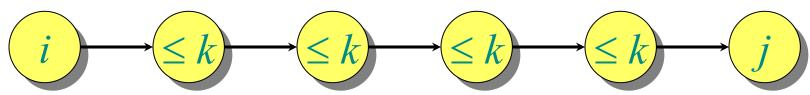
- Run Bellman-Ford once from each vertex.
- Time =  $O(|V|^2|E|)$ .
- But: Dense graph  $\Rightarrow O(|V|^4)$  time.



# Floyd-Warshall algorithm

- Dynamic programming algorithm.
- Assume  $V=\{1, 2, ..., n\}$ , and assume G is given in an adjacency matrix  $A=(a_{ij})_{1 \le i,j \le n}$  where  $a_{ij}$  is the weight of the edge from i to j.

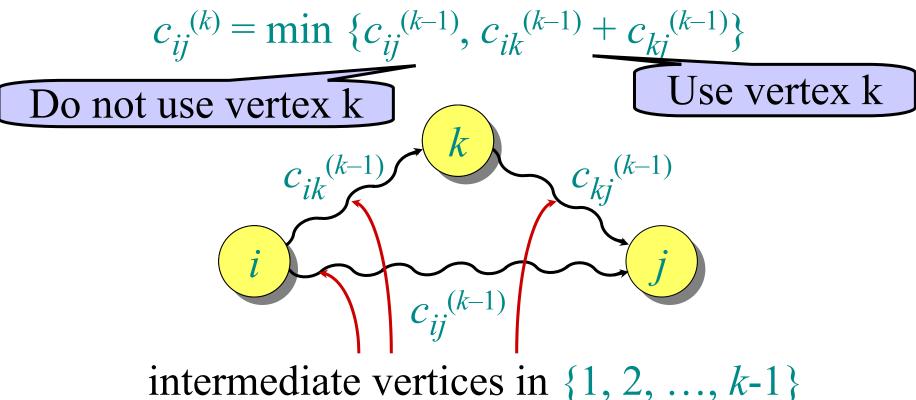
Define  $c_{ij}^{(k)}$  = weight of a shortest path from i to j with intermediate vertices belonging to the set  $\{1, 2, ..., k\}$ .

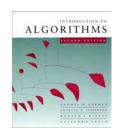


Thus,  $\delta(i,j) = c_{ij}^{(n)}$ . Also,  $c_{ij}^{(0)} = a_{ij}$ .



# Floyd-Warshall recurrence





# Pseudocode for Floyd-Warshall

```
for k \leftarrow 1 to n do

for i \leftarrow 1 to n do

for j \leftarrow 1 to n do

if c_{ij}^{(k-1)} > c_{ik}^{(k-1)} + c_{kj}^{(k-1)} then

c_{ij}^{(k)} \leftarrow c_{ik}^{(k-1)} + c_{kj}^{(k-1)}

else
```

$$c_{ij}^{(k)} \leftarrow c_{ij}^{(k-1)}$$

- Runs in  $\Theta(n^3)$  time and space
- Simple to code.
- Efficient in practice.



## **Shortest paths**

#### Single-source shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| \log |V|)$
- General: Bellman-Ford: O(|V||E|)
- DAG: One pass of Bellman-Ford: O(|V|)

#### All-pairs shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm |V| times:  $O(|V||E| \log |V|)$
- General
  - Bellman-Ford |V| times: O(|V| <sup>2</sup>|E|)
    Floyd-Warshall: O(|V| <sup>3</sup>)

adj. list adi. matrix

adj. list



# Johnson's algorithm

- 1. Compute a weight function  $\hat{w}$  from w such that  $\hat{w}(u, v) \ge 0$  for all  $(u, v) \in E$ . (Or determine that a negative-weight cycle exists, and stop.)
  - Can be done in O(|V||E|) time (details skipped)
- 2. Run Dijkstra's algorithm from each vertex using  $\hat{w}$ .
  - Time =  $O(|V||E| \log |V|)$ .
- 3. Reweight each shortest-path length  $\hat{w}(p)$  to produce the shortest-path lengths w(p) of the original graph.
  - Time =  $O(|V|^2)$  (details skipped)

Total time =  $O(|V||E|\log|V|)$ .



# **Shortest paths**

#### Single-source shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| \log |V|)$
- General: Bellman-Ford: O(|V||E|)
- DAG: One pass of Bellman-Ford: O(|V| + |E|)

#### All-pairs shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm |V| times:  $O(|V||E| \log |V|)$
- General
  - Bellman-Ford |V| times:  $O(|V|^2|E|)$
  - Floyd-Warshall:  $O(|V|^3)$
  - Johnson's algorithm:  $O(|V| |E| \log |V|)$

adj. list adj. matrix adj. list

adj. list