#### **CMPS 2200 – Fall 2014**

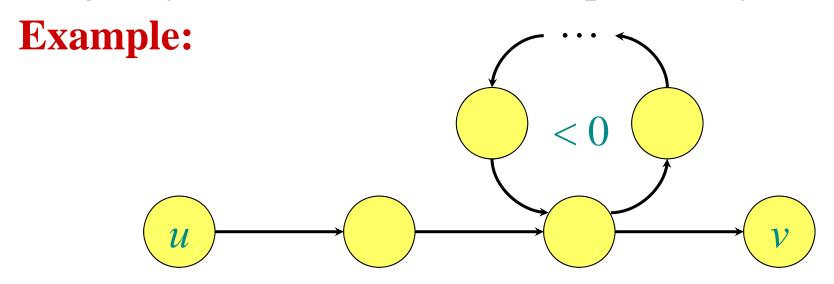
#### More on Shortest Paths

#### Carola Wenk

Slides courtesy of Charles Leiserson with changes by Carola Wenk

# Negative-weight cycles

**Recall:** If a graph G = (V, E) contains a negative-weight cycle, then some shortest paths may not exist.



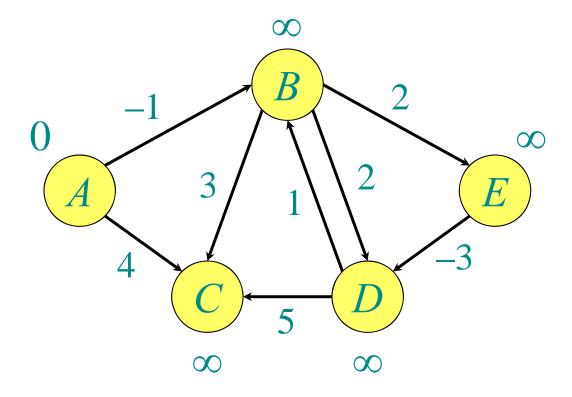
**Bellman-Ford algorithm:** Finds all shortest-path weights from a **source**  $s \in V$  to all  $v \in V$  or determines that a negative-weight cycle exists.

# Bellman-Ford algorithm

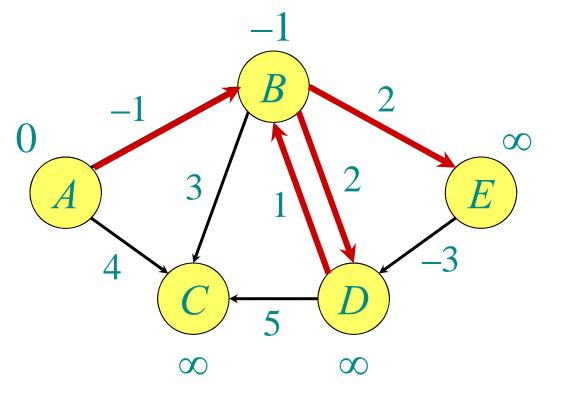
```
for i \leftarrow 1 to |V| - 1 do
  for each edge (u, v) \in E do
    if d[v] > d[u] + w(u, v) then d[v] \leftarrow d[u] + w(u, v) step \pi[v] \leftarrow u
for each edge (u, v) \in E
   do if d[v] > d[u] + w(u, v)
          then report that a negative-weight cycle exists
```

At the end,  $d[v] = \delta(s, v)$ . Time = O(|V||E|).

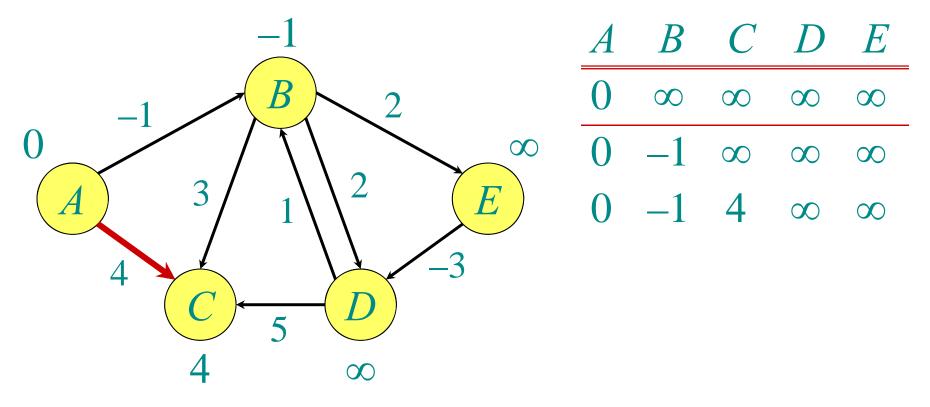
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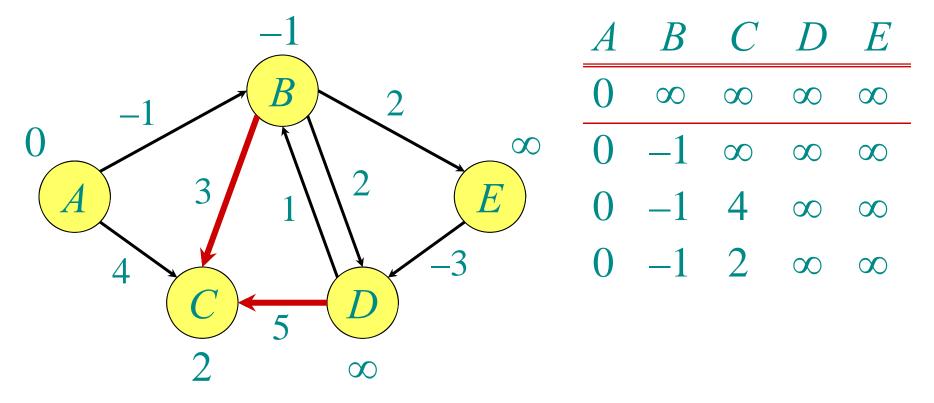


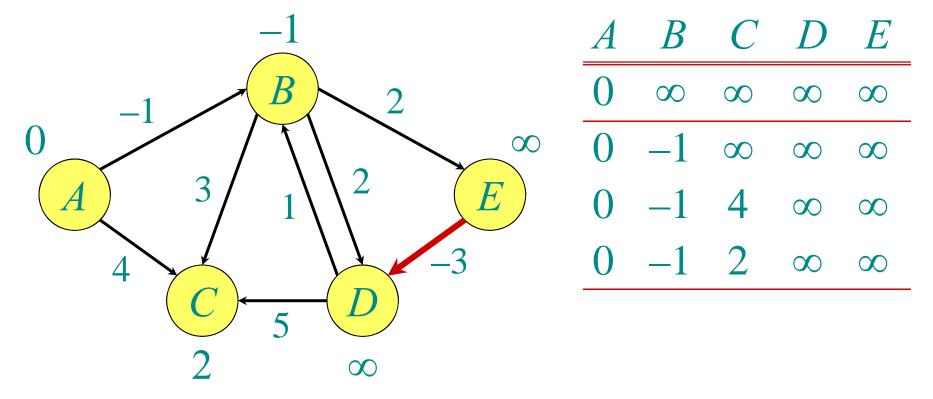
A	$\boldsymbol{B}$	$\boldsymbol{C}$	D	$\boldsymbol{E}$
0	$\infty$	$\infty$	$\infty$	$\infty$

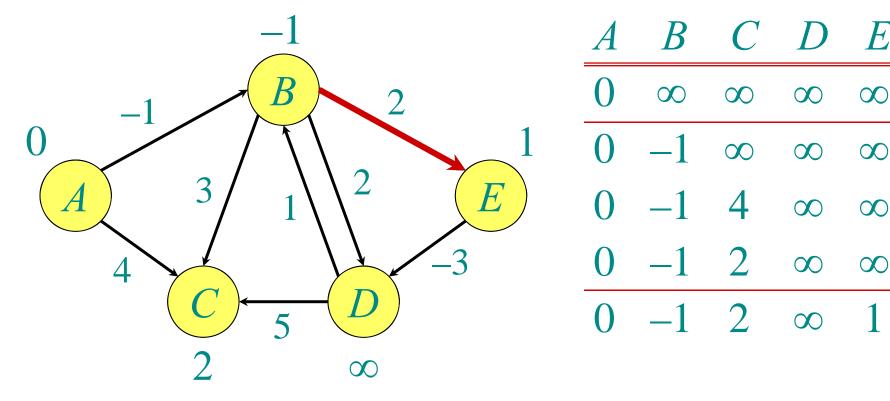


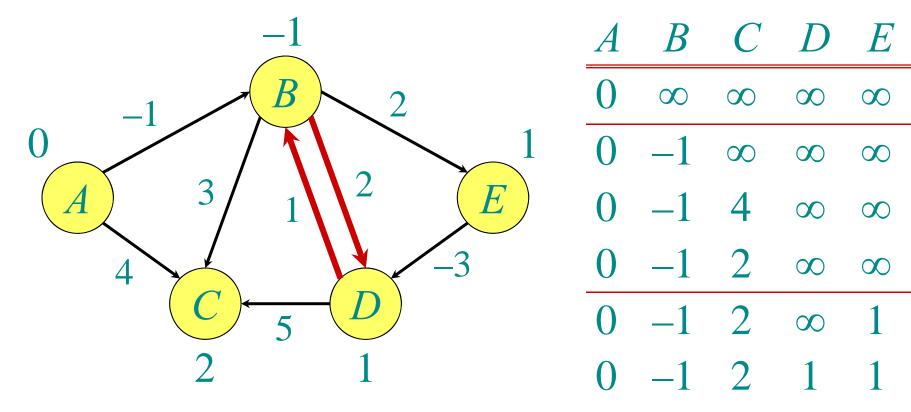
A	$\boldsymbol{B}$	$\boldsymbol{C}$	D	$\boldsymbol{E}$
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$

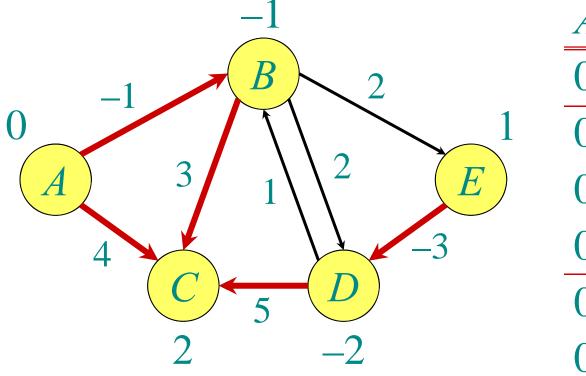






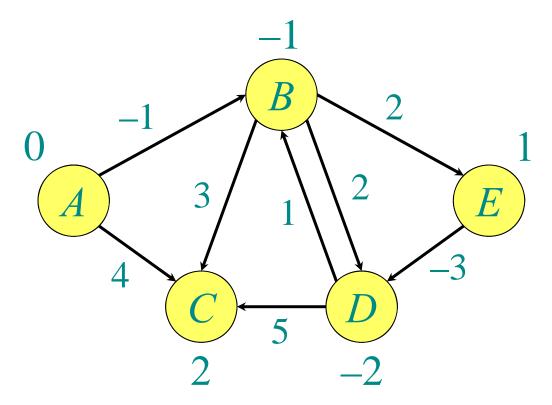






A	$\boldsymbol{B}$	$\boldsymbol{C}$	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$
0	-1	2	$\infty$	1
0	-1	2	1	1
0	<b>-1</b>	2	<b>-2</b>	1

Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



**Note:** Values decrease monotonically.

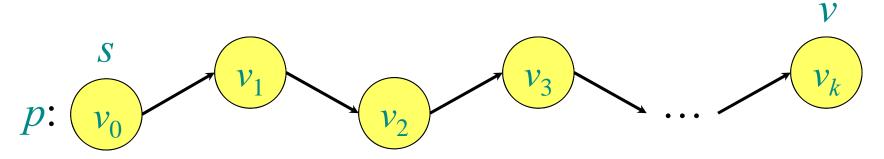
$$A \ B \ C \ D \ E$$
 $0 \ \infty \ \infty \ \infty$ 
 $0 \ -1 \ \infty \ \infty \ \infty$ 
 $0 \ -1 \ 4 \ \infty \ \infty$ 
 $0 \ -1 \ 2 \ \infty \ 1$ 
 $0 \ -1 \ 2 \ 1 \ 1$ 
 $0 \ -1 \ 2 \ -2 \ 1$ 
... and 2 more iterations

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#### **Correctness**

**Theorem.** If G = (V, E) contains no negative-weight cycles, then after the Bellman-Ford algorithm executes,  $d[v] = \delta(s, v)$  for all  $v \in V$ .

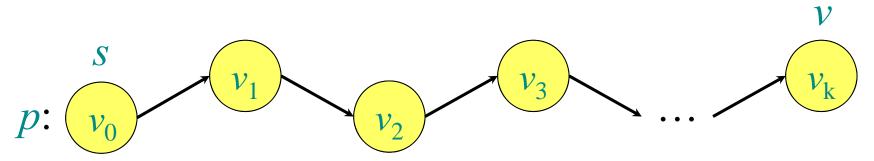
**Proof.** Let  $v \in V$  be any vertex, and consider a shortest path p from s to v with the minimum number of edges.



Since *p* is a shortest path, we have

$$\delta(s, v_i) = \delta(s, v_{i-1}) + w(v_{i-1}, v_i).$$

## **Correctness** (continued)



Initially,  $d[v_0] = 0 = \delta(s, v_0)$ , and d[s] is unchanged by subsequent relaxations.

- After 1 pass through E, we have  $d[v_1] = \delta(s, v_1)$ .
- After 2 passes through E, we have  $d[v_2] = \delta(s, v_2)$ .

• • •

• After k passes through E, we have  $d[v_k] = \delta(s, v_k)$ . Since G contains no negative-weight cycles, p is simple. Longest simple path has  $\leq |V| - 1$  edges.

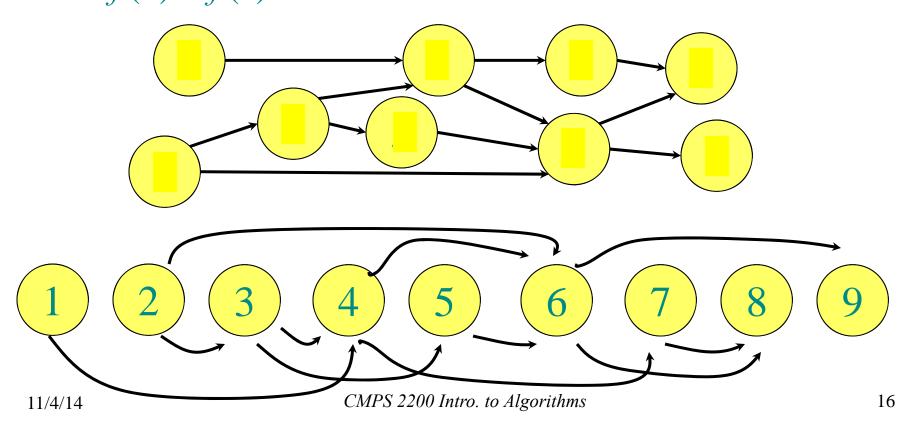
# Detection of negative-weight cycles

**Corollary.** If a value d[v] fails to converge after |V| - 1 passes, there exists a negative-weight cycle in G reachable from s.

#### DAG shortest paths

If the graph is a *directed acyclic graph* (*DAG*), we first *topologically sort* the vertices.

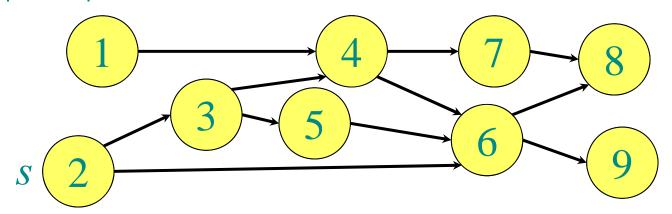
• Determine  $f: V \to \{1, 2, ..., |V|\}$  such that  $(u, v) \in E$  $\Rightarrow f(u) < f(v)$ .



## DAG shortest paths

If the graph is a *directed acyclic graph* (*DAG*), we first *topologically sort* the vertices.

- Determine  $f: V \to \{1, 2, ..., |V|\}$  such that  $(u, v) \in E$  $\Rightarrow f(u) < f(v)$ .
- O(|V| + |E|) time



• Walk through the vertices  $u \in V$  in this order, relaxing the edges in Adj[u], thereby obtaining the shortest paths from s in a total of O(|V| + |E|) time.

## **Shortest paths**

#### Single-source shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| \log |V|)$
- General: Bellman-Ford: O(|V||E|)
- DAG: One pass of Bellman-Ford: O(|V| + |E|)

## **Shortest paths**

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#### **All-pairs shortest paths**

- Nonnegative edge weights
  - Dijkstra's algorithm |V| times:  $O(|V||E| \log |V|)$
- General
  - Bellman-Ford |V| times:  $O(|V|^2|E|)$
  - Floyd-Warshall:  $O(|V|^3)$