

2. Homework (undergrad)

Due 1/30/20 before class

1. Line segment intersection (10 points)

Given two line segments \overline{ab} and \overline{cd} in the plane, where $a, b, c, d \in \mathbb{R}^2$. The goal is to test them for intersection.

- (a) (3 points) Let $a = \begin{pmatrix} 6 \\ 5 \end{pmatrix}$, $b = \begin{pmatrix} 14 \\ 9 \end{pmatrix}$, $c = \begin{pmatrix} 7 \\ 2 \end{pmatrix}$, and $d = \begin{pmatrix} 9 \\ 10 \end{pmatrix}$. Express each line segment as a convex combination, and use this representation to determine if \overline{ab} and \overline{cd} intersect, and if so, compute their intersection point.
- (b) (2 points) Do \overline{eb} and \overline{cd} intersect, where $e = \begin{pmatrix} 10 \\ 7 \end{pmatrix}$? What is different compared to part (a)?
- (c) (5 points) Explain how you can use one or more orientation tests to test if two line segments intersect. (*Hint: Case analysis. Draw pictures of examples, and determine important configurations of a, b, c, d .*)

2. Lower bounds (3 points)

Prove a lower bound of $\Omega(n \log n)$ for SORTING, by reducing from ELEMENT UNIQUENESS (i.e., by using the knowledge that ELEMENT UNIQUENESS has a lower bound of $\Omega(n \log n)$).

3. Visible Segments Sweep (10 points)

Let S be a set of n disjoint line segments in the plane, and let p be a point not on any of the line segments of S . We say that the point p sees a line segment s if there is a point $q \in s$ such that the segment pq does not intersect any other line segment of S . We wish to determine all line segments of S that p can see.

Give an $O(n \log n)$ time algorithm for this problem that uses a rotating half-line with its endpoint at p to sweep the plane. You do not have to give pseudocode but you should explain all the necessary components of the sweep.

