

## 2. Homework (grad)

Due **1/30/20** before class

### 1. Line segment intersection (5 points)

Explain how you can use one or more orientation tests to test if two line segments  $\overline{ab}$  and  $\overline{cd}$  intersect, where  $a, b, c, d \in \mathbb{R}^2$ . (*Hint: Case analysis. Draw pictures of examples, and determine important configurations of  $a, b, c, d$ .*)

### 2. Lower bounds (9 points)

Consider the following problems:

**SORTING:** Given a set  $X = \{x_1, \dots, x_n\}$  of  $n$  numbers, output the same numbers in non-decreasing order.

**ELEMENT UNIQUENESS:** Given a set  $X = \{x_1, \dots, x_n\}$  of  $n$  numbers, are there  $i, j$ , with  $i \neq j$ , such that  $x_i = x_j$ ?

**CLOSEST PAIR:** Given a point set  $P = \{p_1, \dots, p_n\} \in \mathbb{R}^2$ , output the closest pair of points in  $P$ .

**ALL NEAREST NEIGHBORS:** Given a point set  $P = \{p_1, \dots, p_n\} \in \mathbb{R}^2$ . Compute for each point in  $P$  its *nearest neighbor* in  $P$  (i.e., point at minimum distance).

- Prove a lower bound of  $\Omega(n \log n)$  for SORTING, by reducing from ELEMENT UNIQUENESS (i.e., by using the knowledge that ELEMENT UNIQUENESS has a lower bound of  $\Omega(n \log n)$ ).
- Prove a lower bound of  $\Omega(n \log n)$  for CLOSEST PAIR by reducing from an appropriate problem.
- Prove a lower bound of  $\Omega(n \log n)$  for ALL NEAREST NEIGHBORS by reducing from an appropriate problem.

### 3. Visible Segments Sweep (10 points)

Let  $S$  be a set of  $n$  disjoint line segments in the plane, and let  $p$  be a point not on any of the line segments of  $S$ . We say that the point  $p$  *sees* a line segment  $s$  if there is a point  $q \in s$  such that the segment  $pq$  does not intersect any other line segment of  $S$ . We wish to determine all line segments of  $S$  that  $p$  can see.

Give an  $O(n \log n)$  time algorithm for this problem that uses a rotating half-line with its endpoint at  $p$  to sweep the plane. You do not have to give pseudocode but you should explain all the necessary components of the sweep.

