

**CMPS 2200 – Fall 2017**

***Single Source Shortest Paths***

**Carola Wenk**

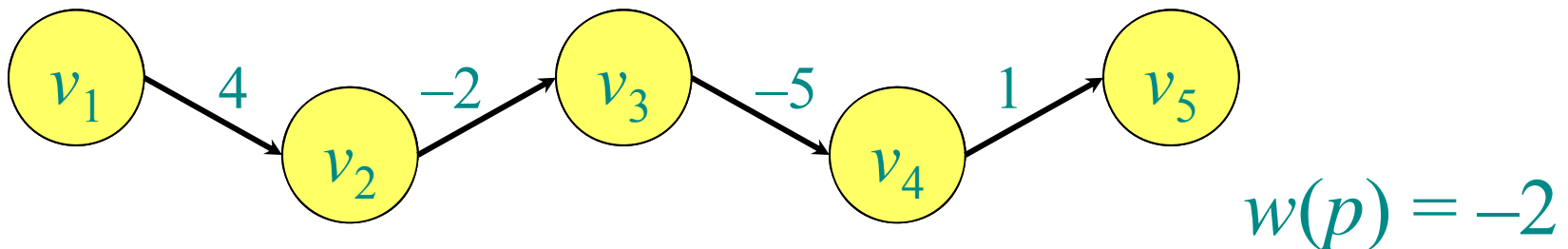
Slides courtesy of Charles Leiserson with changes  
and additions by Carola Wenk

# Paths in graphs

Consider a digraph  $G = (V, E)$  with an edge-weight function  $w : E \rightarrow \mathbb{R}$ . The **weight** of path  $p = v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_k$  is defined to be

$$w(p) = \sum_{i=1}^{k-1} w(v_i, v_{i+1}).$$

**Example:**



# Shortest paths

A *shortest path* from  $u$  to  $v$  is a path of minimum weight from  $u$  to  $v$ .

The *shortest-path weight* from  $u$  to  $v$  is defined as

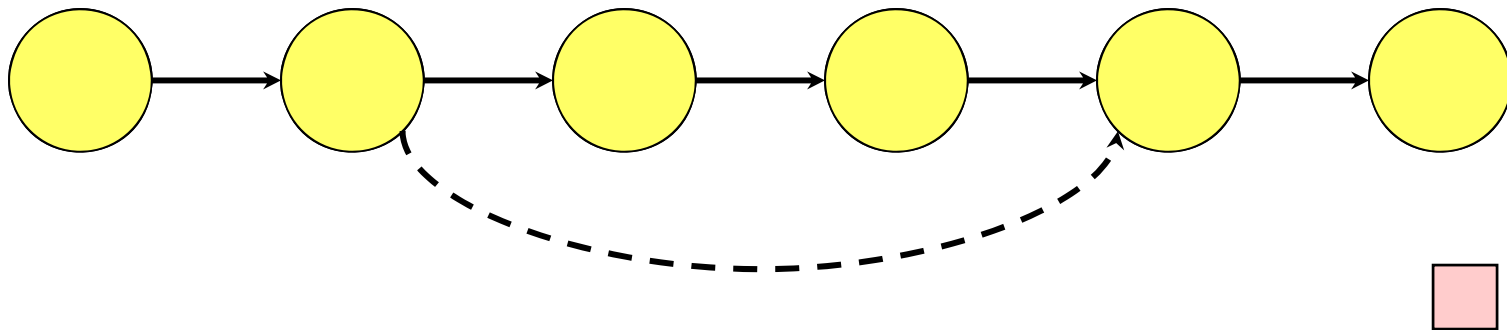
$$\delta(u, v) = \min \{w(p) : p \text{ is a path from } u \text{ to } v\}.$$

**Note:**  $\delta(u, v) = \infty$  if no path from  $u$  to  $v$  exists.

# Optimal substructure

**Theorem.** A subpath of a shortest path is a shortest path.

*Proof.* Cut and paste:

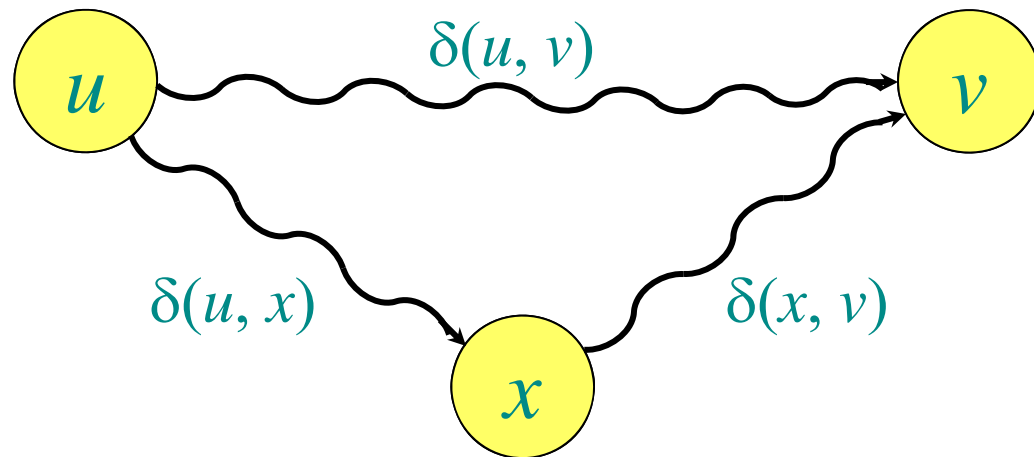


# Triangle inequality

**Theorem.** For all  $u, v, x \in V$ , we have  
$$\delta(u, v) \leq \delta(u, x) + \delta(x, v).$$

*Proof.*

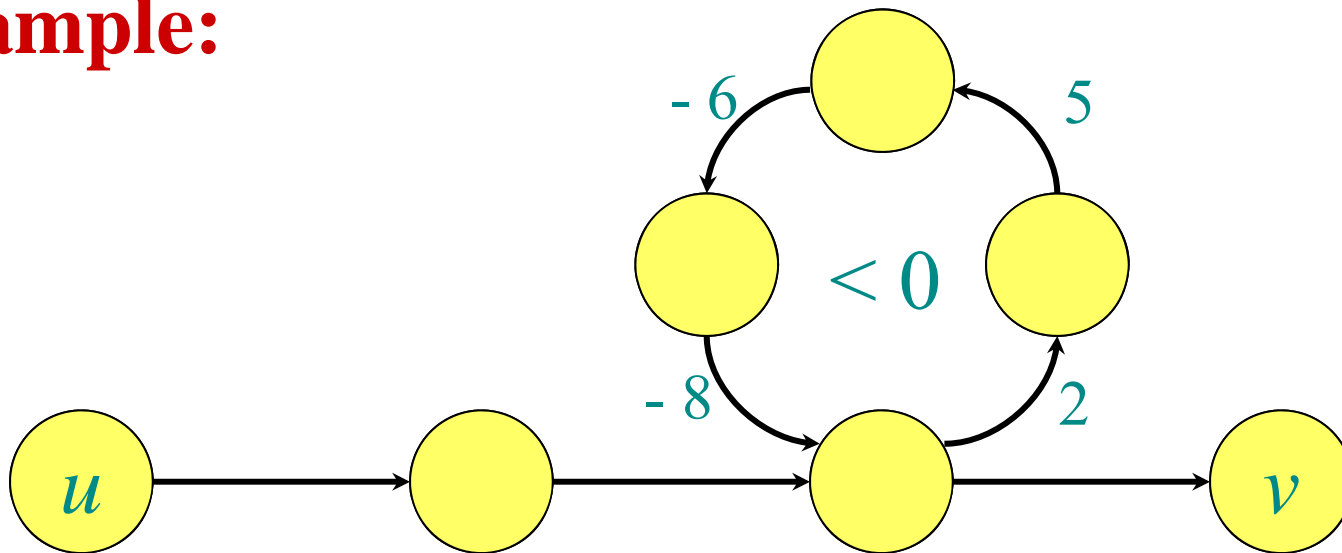
- $\delta(u, v)$  minimizes over **all** paths from  $u$  to  $v$
- Concatenating two shortest paths from  $u$  to  $x$  and from  $x$  to  $v$  yields **one** specific path from  $u$  to  $v$



# Well-definedness of shortest paths

If a graph  $G$  contains a negative-weight cycle, then some shortest paths may not exist.

**Example:**



# Single-source shortest paths

**Problem.** From a given source vertex  $s \in V$ , find the shortest-path weights  $\delta(s, v)$  for all  $v \in V$ .

## Assumption:

All edge weights  $w(u, v)$  are *non-negative*.

It follows that all shortest-path weights must exist.

## IDEA: Greedy.

1. Maintain a set  $S$  of vertices whose shortest-path weights from  $s$  are known, i.e.,  $d[v] = \delta(s, v)$
2. At each step add to  $S$  the vertex  $u \in V - S$  whose distance estimate  $d[u]$  from  $s$  is minimal.
3. Update the distance estimates  $d[v]$  of vertices  $v$  adjacent to  $u$ .

# Dijkstra's algorithm

$d[s] \leftarrow 0$

**for each**  $v \in V - \{s\}$  **do**

$d[v] \leftarrow \infty$

$S \leftarrow \emptyset$

▷ Vertices for which  $d[v]=d(s,v)$

$Q \leftarrow V$

▷  $Q$  is a priority queue maintaining  $V - S$   
sorted by  $d$ -values  $d[v]$

**while**  $Q \neq \emptyset$  **do**

$u \leftarrow Q.\text{EXTRACT-MIN}()$

$S \leftarrow S \cup \{u\}$

**for each**  $v \in \text{Adj}[u]$  **do**

**if**  $d[v] > d[u] + w(u, v)$  **then**  
 $d[v] \leftarrow d[u] + w(u, v)$

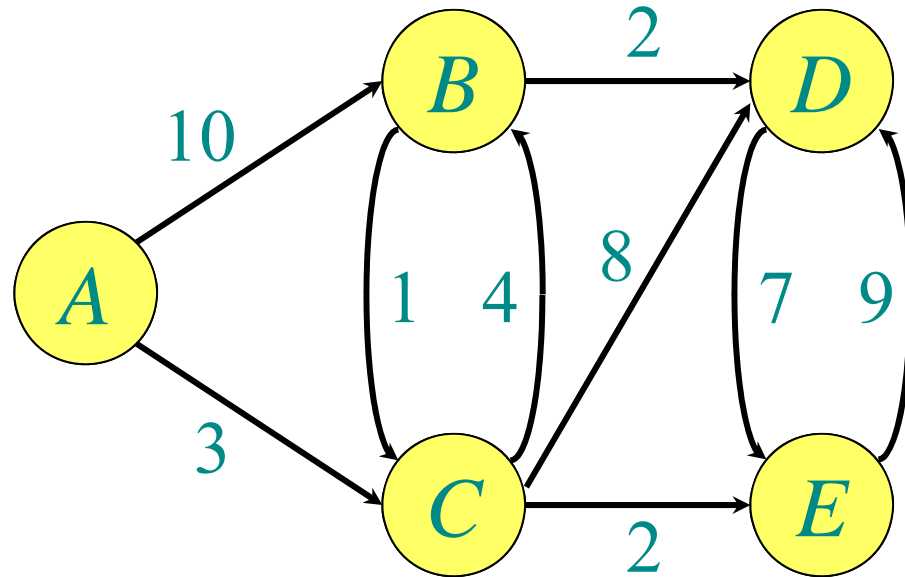
*relaxation step*

implicit  $Q.\text{DECREASE-KEY}$



# Example of Dijkstra's algorithm

Graph with nonnegative edge weights:



```
while  $Q \neq \emptyset$  do
   $u \leftarrow Q.\text{EXTRACT-MIN}()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in \text{Adj}[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
```

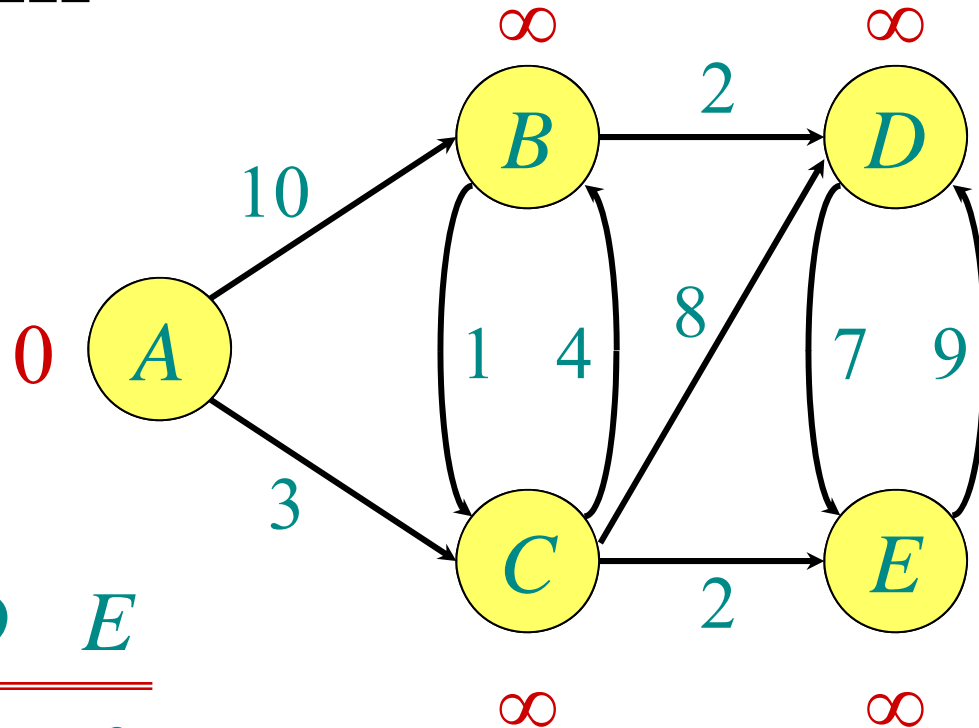
# Example of Dijkstra's algorithm

**Initialize:**

$S: \{\}$

$Q:$

<u>A</u>	<u>B</u>	<u>C</u>	<u>D</u>	<u>E</u>
0	$\infty$	$\infty$	$\infty$	$\infty$



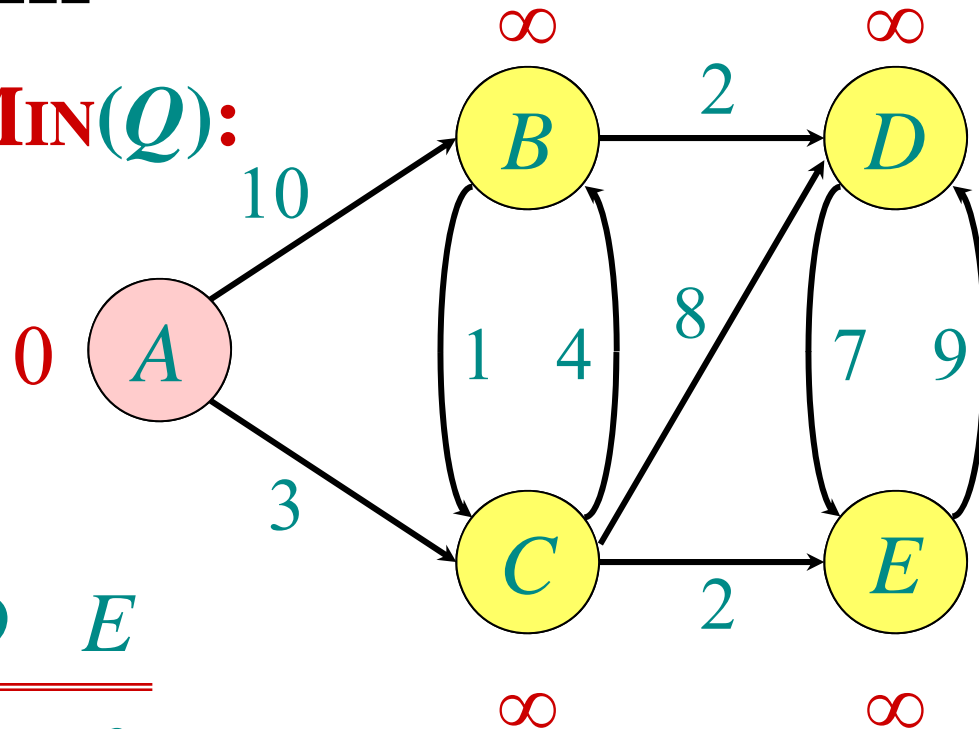
```
while  $Q \neq \emptyset$  do
   $u \leftarrow Q.\text{EXTRACT-MIN}()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in \text{Adj}[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
```

# Example of Dijkstra's algorithm

“A” ← **EXTRACT-MIN**(Q):

S: { A }

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$

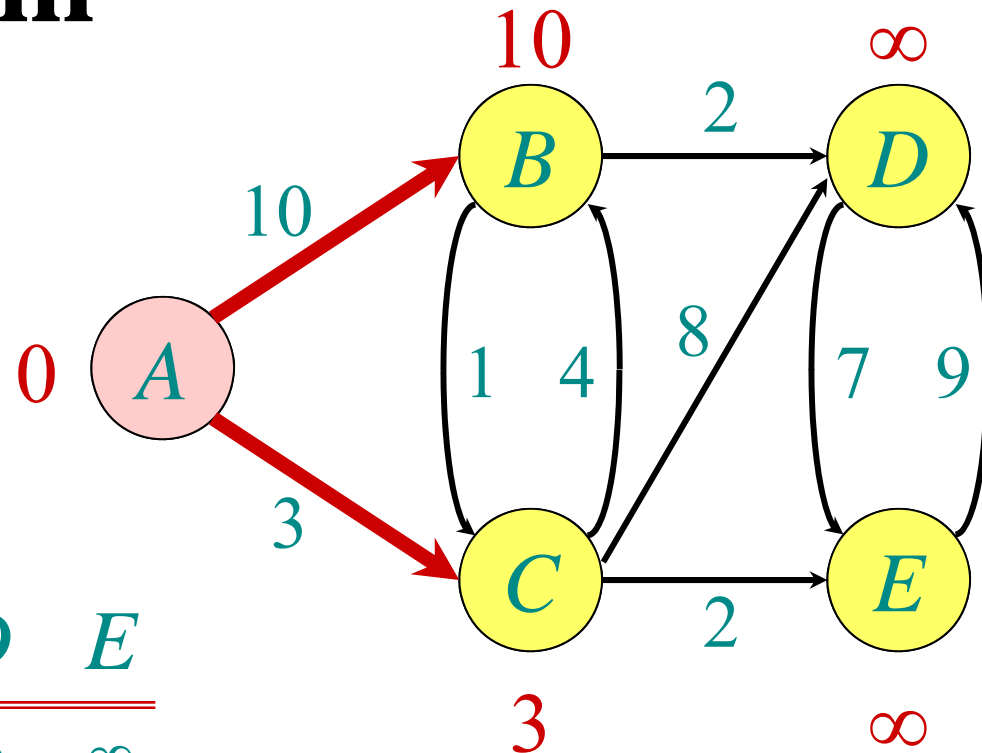


```
while Q ≠ ∅ do
  u ← Q.EXTRACT-MIN()
  S ← S ∪ {u}
  for each v ∈ Adj[u] do
    if d[v] > d[u] + w(u, v) then
      d[v] ← d[u] + w(u, v)
```

# Example of Dijkstra's algorithm

Relax all edges leaving  $A$ :

$S: \{A\}$



$Q:$	$A$	$B$	$C$	$D$	$E$
	0	$\infty$	$\infty$	$\infty$	$\infty$
		10	3	-	-

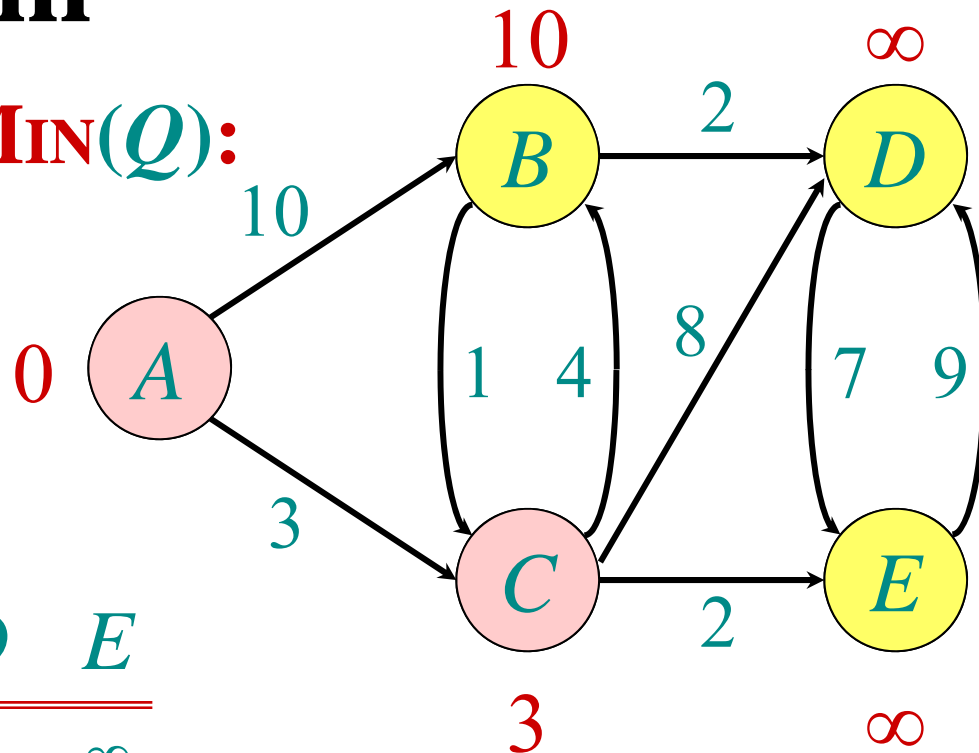
```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.\text{EXTRACT-MIN}()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in \text{Adj}[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
    
```

# Example of Dijkstra's algorithm

“C” ← **EXTRACT-MIN**(Q):

S: { A, C }



Q:	A	B	C	D	E
	0	∞	∞	∞	∞
		10	3	-	-

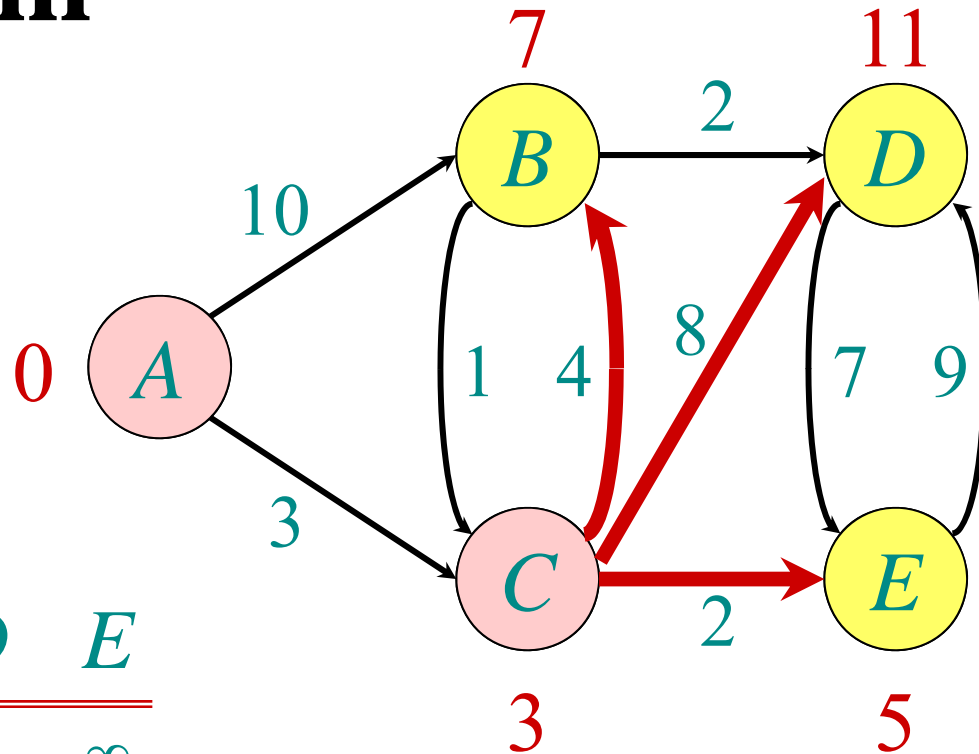
```

while Q ≠ ∅ do
  u ← Q.EXTRACT-MIN()
  S ← S ∪ {u}
  for each v ∈ Adj[u] do
    if d[v] > d[u] + w(u, v) then
      d[v] ← d[u] + w(u, v)
  
```

# Example of Dijkstra's algorithm

Relax all edges leaving  $C$ :

$S: \{A, C\}$



$Q:$

$A$	$B$	$C$	$D$	$E$
0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	—	—
	7		11	5

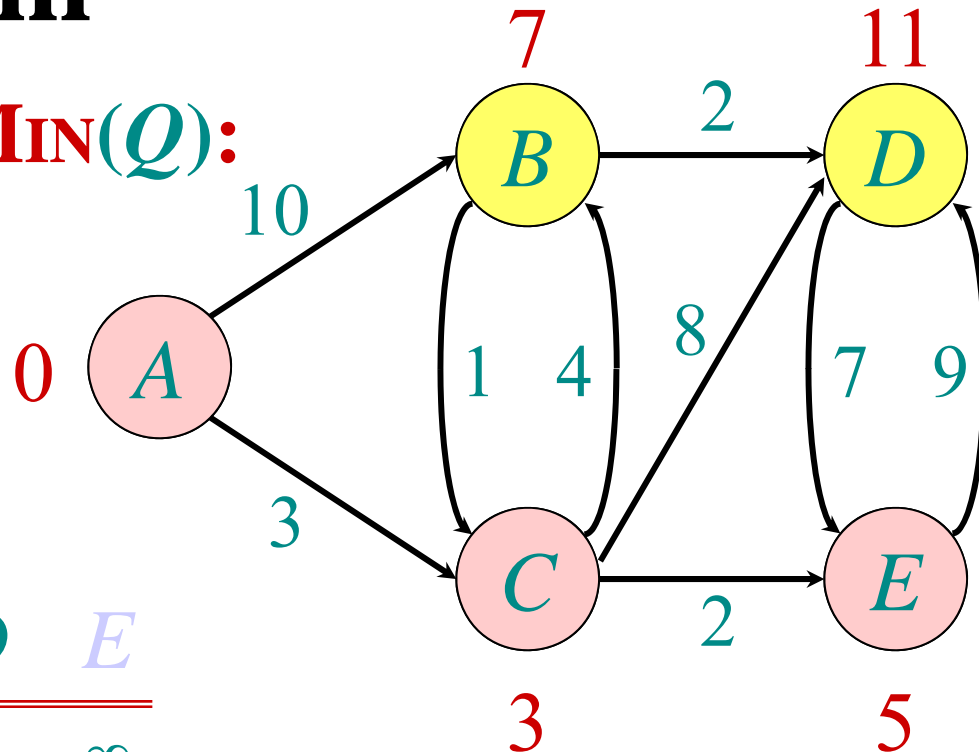
```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
    
```

# Example of Dijkstra's algorithm

“E” ← **EXTRACT-MIN(Q)**:

$S: \{A, C, E\}$



$Q:$	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
		10	3	–	–
		7		11	5

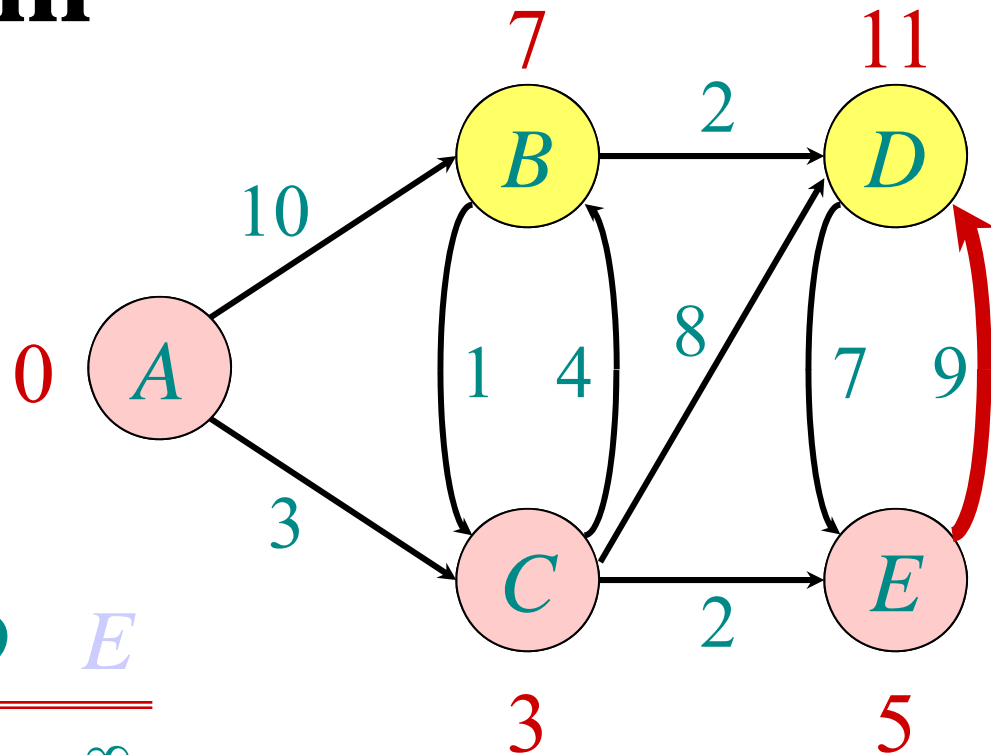
```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.$ EXTRACT-MIN()
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
  
```

# Example of Dijkstra's algorithm

Relax all edges leaving  $E$ :

$S: \{A, C, E\}$



$Q:$

$A$	$B$	$C$	$D$	$E$
0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	$\infty$	$\infty$
	7		11	5
	7		11	

```

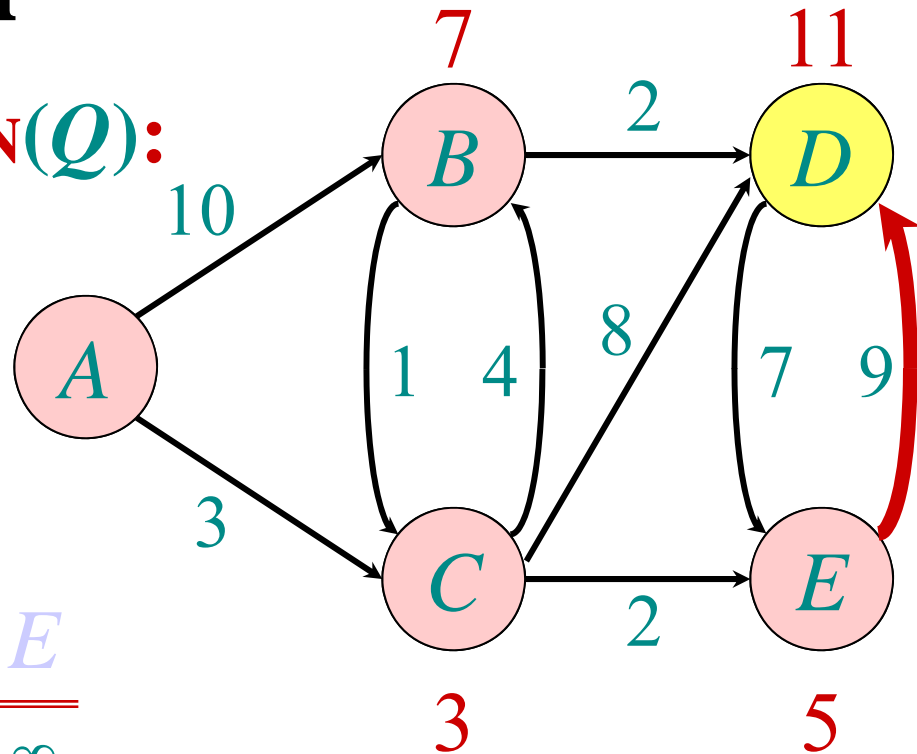
while  $Q \neq \emptyset$  do
   $u \leftarrow Q.$ EXTRACT-MIN()
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
  
```



# Example of Dijkstra's algorithm

“B” ← **EXTRACT-MIN(Q)**:

$S: \{A, C, E, B\}$     0



$Q:$	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
		10	3	$\infty$	$\infty$
		7		11	5
		7		11	

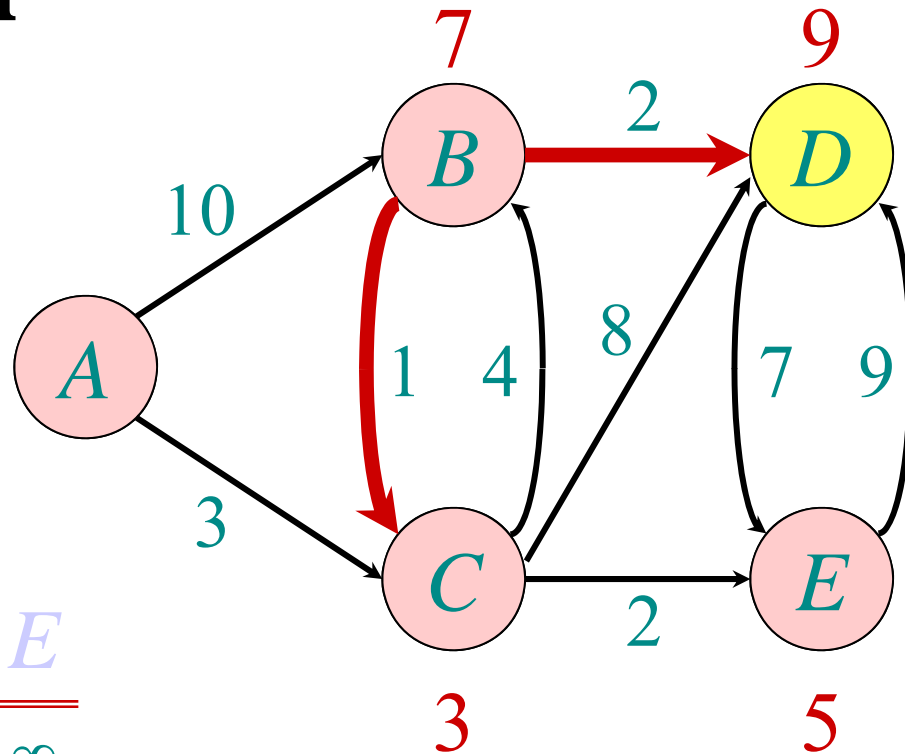
```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.$ EXTRACT-MIN()
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
    
```

# Example of Dijkstra's algorithm

Relax all edges leaving  $B$ :

$S: \{A, C, E, B\}$      0



$Q:$

$A$	$B$	$C$	$D$	$E$
0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	$\infty$	$\infty$
	7		11	5
	7		11	
			9	

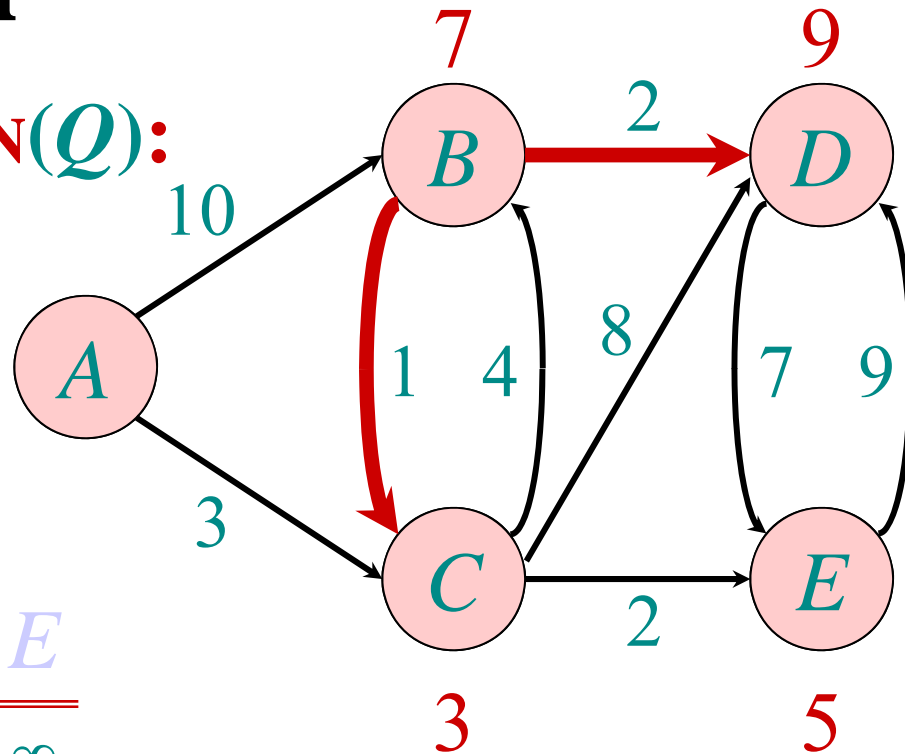
```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
    
```

# Example of Dijkstra's algorithm

“D” ← **EXTRACT-MIN(Q)**:

S: { A, C, E, B, D } 0



Q:

A	B	C	D	E
0	∞	∞	∞	∞
	10	3	∞	∞
	7		11	5
	7		11	
			9	

```

while Q ≠ ∅ do
  u ← Q.EXTRACT-MIN()
  S ← S ∪ {u}
  for each v ∈ Adj[u] do
    if d[v] > d[u] + w(u, v) then
      d[v] ← d[u] + w(u, v)
  
```

# Analysis of Dijkstra

$|V|$   
times

$degree(u)$   
times

```
while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
```

Handshaking Lemma  $\Rightarrow \Theta(|E|)$  implicit  $Q.DECREASE-KEY$ 's.

$$\text{Time} = \Theta(|V|) \cdot T_{\text{EXTRACT-MIN}} + \Theta(|E|) \cdot T_{\text{DECREASE-KEY}}$$

# Analysis of Dijkstra (continued)

$$\text{Time} = \Theta(|V|) \cdot T_{\text{EXTRACT-MIN}} + \Theta(|E|) \cdot T_{\text{DECREASE-KEY}}$$

$Q$	$T_{\text{EXTRACT-MIN}}$	$T_{\text{DECREASE-KEY}}$	Total
array	$O( V )$	$O(1)$	$O( V ^2)$
binary heap	$O(\log  V )$	$O(\log  V )$	$O( E  \log  V )$
Fibonacci heap	$O(\log  V )$ amortized	$O(1)$ amortized	$O( E  +  V  \log  V )$ worst case

# Correctness

**Theorem.** (i) For all  $v \in S$ :  $d[v] = \delta(s, v)$   
(ii) For all  $v \notin S$ :  $d[v] =$  weight of shortest path from  $s$  to  $v$  that uses only (besides  $v$  itself) vertices in  $S$ .

**Corollary.** Dijkstra's algorithm terminates with  $d[v] = \delta(s, v)$  for all  $v \in V$ .

# Correctness

**Theorem.** (i) For all  $v \in S$ :  $d[v] = \delta(s, v)$   
(ii) For all  $v \notin S$ :  $d[v] =$  weight of shortest path from  $s$  to  $v$  that uses only (besides  $v$  itself) vertices in  $S$ .

---

*Proof.* By induction.

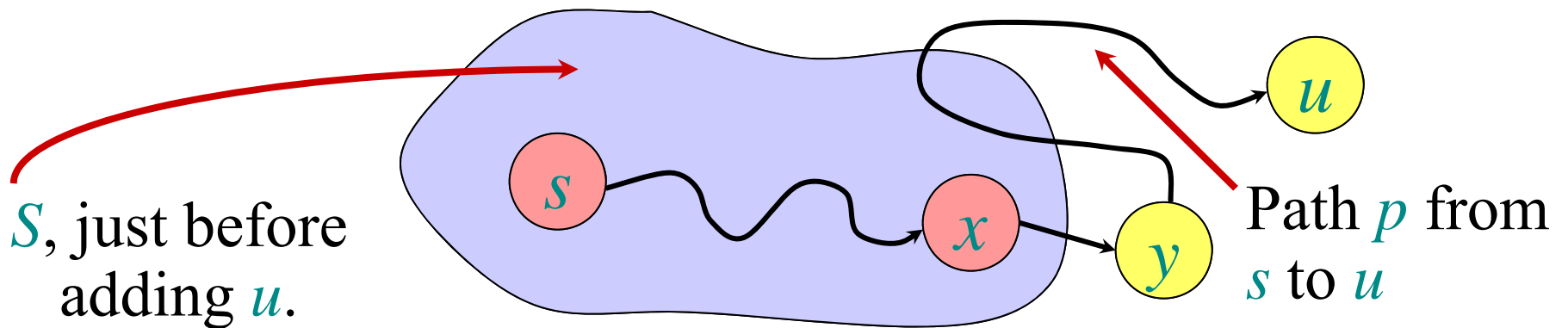
- Base: Before the while loop,  $d[s]=0$  and  $d[v]=\infty$  for all  $v \neq s$ , so (i) and (ii) are true.
- Step: Assume (i) and (ii) are true before an iteration; now we need to show they remain true after another iteration. Let  $u$  be the vertex added to  $S$ , so  $d[u] \leq d[v]$  for all other  $v \notin S$ .

# Correctness

**Theorem.** (i) For all  $v \in S$ :  $d[v] = \delta(s, v)$   
(ii) For all  $v \notin S$ :  $d[v] =$  weight of shortest path from  $s$  to  $v$  that uses only (besides  $v$  itself) vertices in  $S$ .

---

- (i) Need to show that  $d[u] = \delta(s, u)$ . Assume the contrary.  
 $\Rightarrow$  There is a path  $p$  from  $s$  to  $u$  with  $w(p) < d[u]$ . Because of (ii) that path uses vertices  $\notin S$ , in addition to  $u$ .  
 $\Rightarrow$  Let  $y$  be first vertex on  $p$  such that  $y \notin S$ .

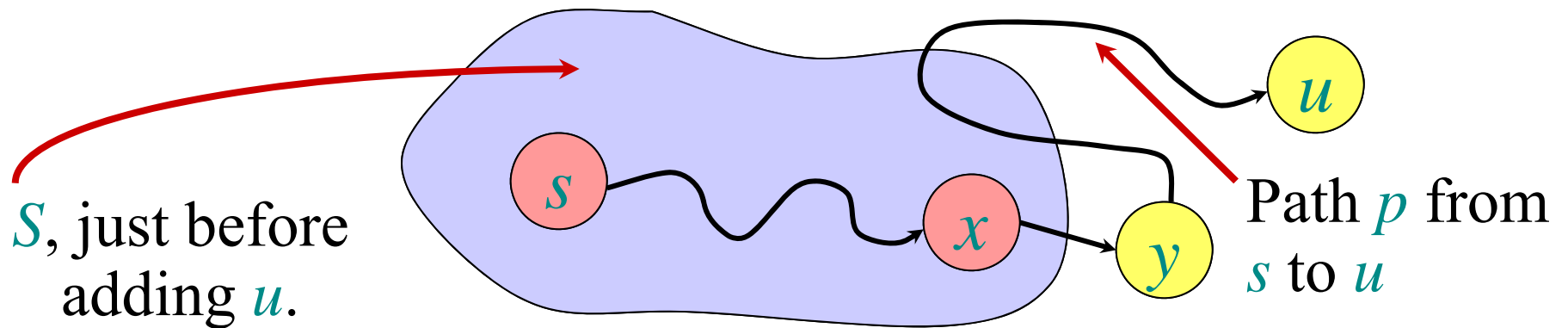




# Correctness

**Theorem.** (i) For all  $v \in S$ :  $d[v] = \delta(s, v)$   
(ii) For all  $v \notin S$ :  $d[v] =$  weight of shortest path from  $s$  to  $v$  that uses only (besides  $v$  itself) vertices in  $S$ .

---



$\Rightarrow d[y] \leq w(p) < d[u]$ . Contradiction to the choice of  $u$ .

weights are nonnegative

assumption about path

# Correctness

**Theorem.** (i) For all  $v \in S$ :  $d[v] = \delta(s, v)$   
(ii) For all  $v \notin S$ :  $d[v] =$  weight of shortest path from  $s$  to  $v$  that uses only (besides  $v$  itself) vertices in  $S$ .

---

- (ii) Let  $v \notin S$ . Let  $p$  be a shortest path from  $s$  to  $v$  that uses only (besides  $v$  itself) vertices in  $S$ .
  - $p$  does not contain  $u$ : (ii) true by inductive hypothesis
  - $p$  contains  $u$ :  $p$  consists of vertices in  $S \setminus \{u\}$  and ends with an edge from  $u$  to  $v$ .  
 $\Rightarrow w(p) = d[u] + w(u, v)$ , which is the value of  $d[v]$  after adding  $u$ . So (ii) is true.

# Unweighted graphs

Suppose  $w(u, v) = 1$  for all  $(u, v) \in E$ . Can the code for Dijkstra be improved?

- Use a simple FIFO queue instead of a priority queue.

- **Breadth-first search**

```
while  $Q \neq \emptyset$  do
```

```
   $u \leftarrow Q.$ DEQUEUE()
```

```
  for each  $v \in Adj[u]$  do
```

```
    if  $d[v] = \infty$  then // unvisited
```

```
       $d[v] \leftarrow d[u] + 1$ 
```

```
       $Q.$ ENQUEUE( $v$ )
```

**Analysis:** Time =  $O(|V| + |E|)$ .

```
while  $Q \neq \emptyset$  do
```

```
   $u \leftarrow Q.$ EXTRACT-MIN()
```

```
   $S \leftarrow S \cup \{u\}$ 
```

```
  for each  $v \in Adj[u]$  do
```

```
    if  $d[v] > d[u] + w(u, v)$  then
```

```
       $d[v] \leftarrow d[u] + w(u, v)$ 
```

# Correctness of BFS

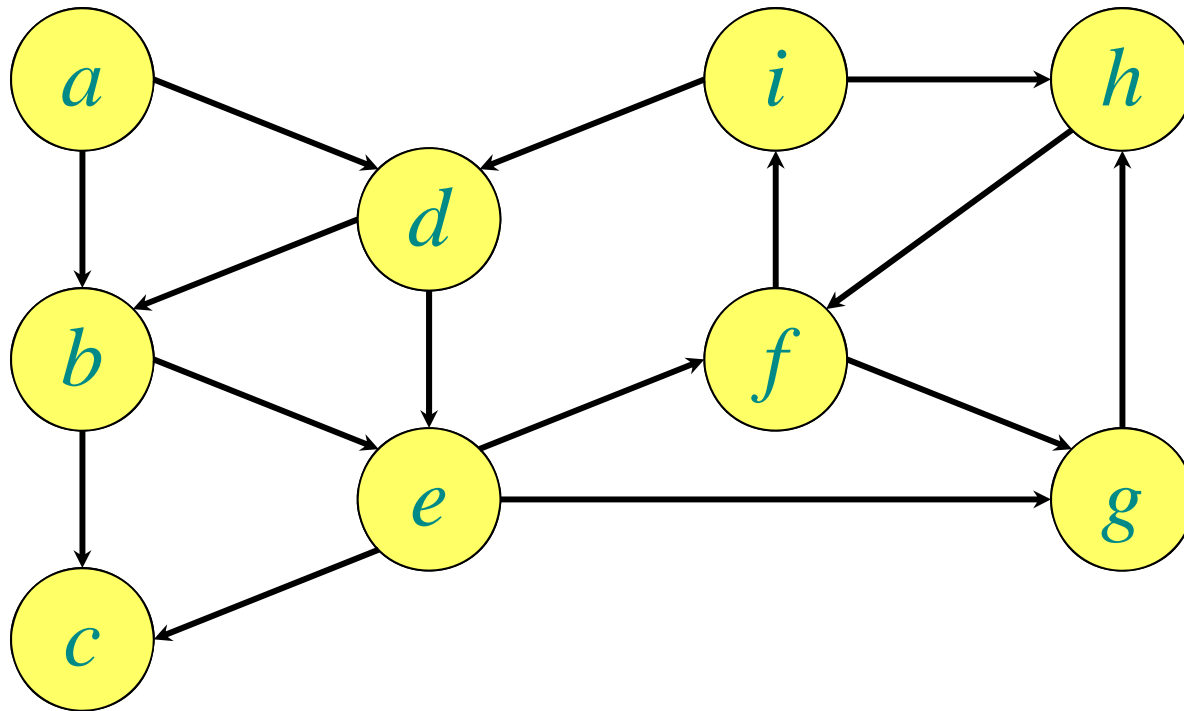
```
while  $Q \neq \emptyset$  do
   $u \leftarrow Q.\text{DEQUEUE}()$ 
  for each  $v \in \text{Adj}[u]$  do
    if  $d[v] = \infty$  then // unvisited
       $d[v] \leftarrow d[u] + 1$ 
       $Q.\text{ENQUEUE}(v)$ 
```

## Key idea:

The FIFO  $Q$  in breadth-first search mimics the priority queue  $Q$  in Dijkstra.

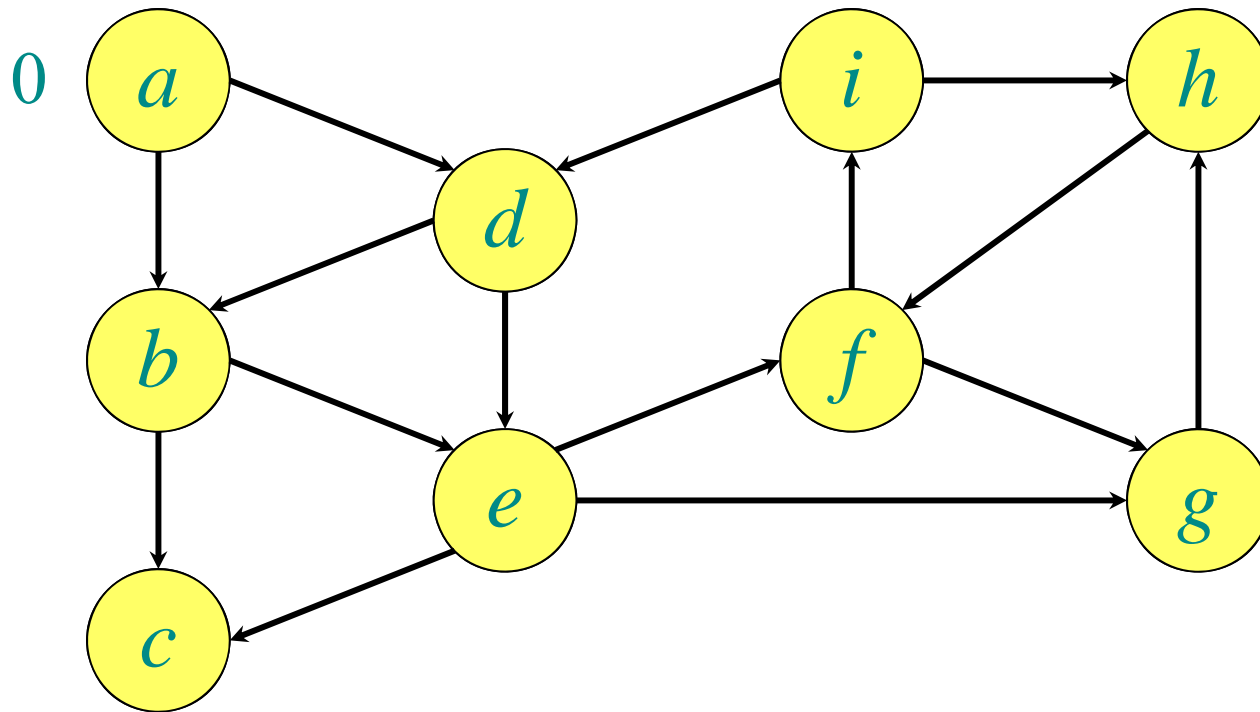
- **Invariant:**  $v$  comes after  $u$  in  $Q$  implies that  $d[v] = d[u]$  or  $d[v] = d[u] + 1$ .

# Example of breadth-first search



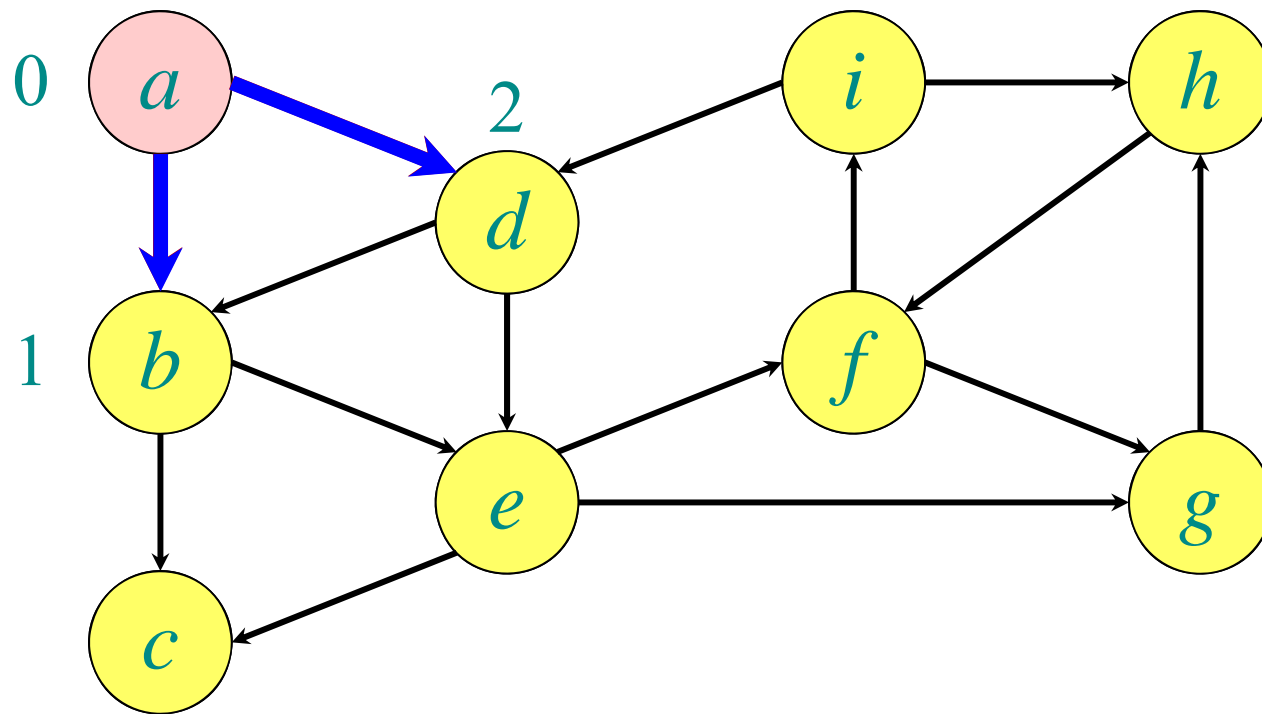
$Q:$   
 $d[v]$

# Example of breadth-first search



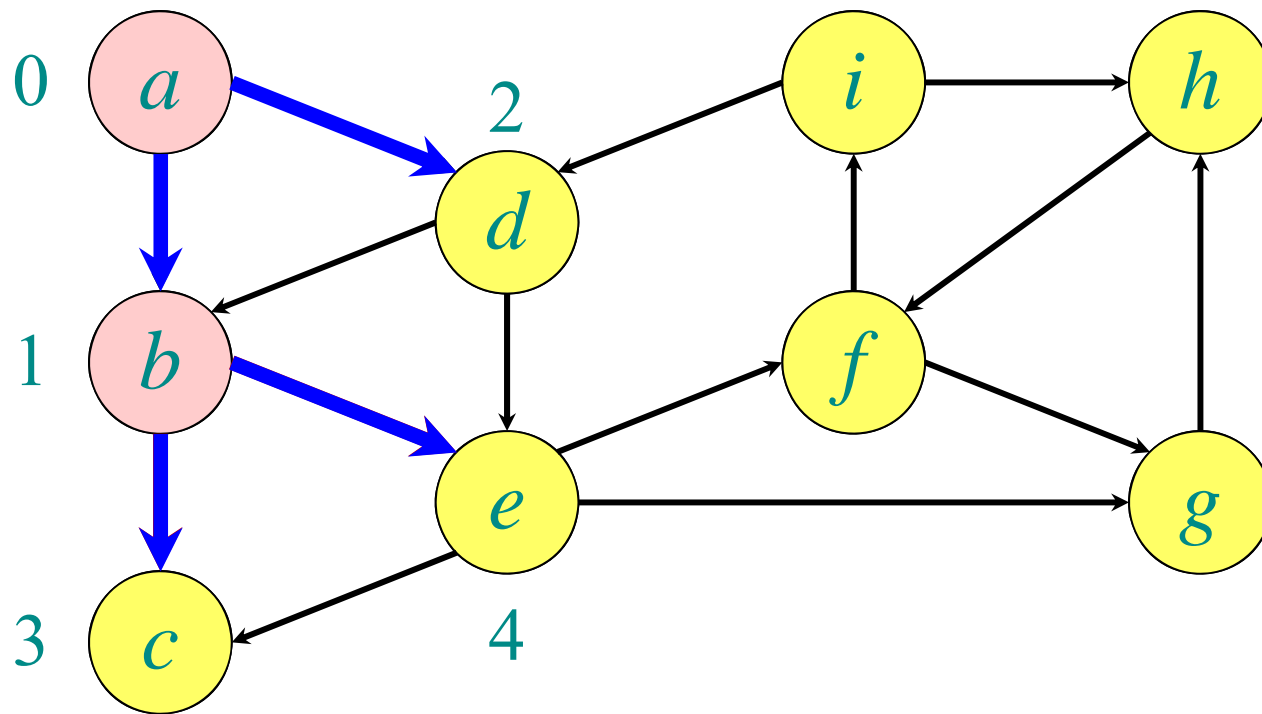
$Q: a$   
 $d[v] 0$

# Example of breadth-first search



1 2  
 $Q:$   $a$   $b$   $d$   
 $d[v]$  0 1 1

# Example of breadth-first search



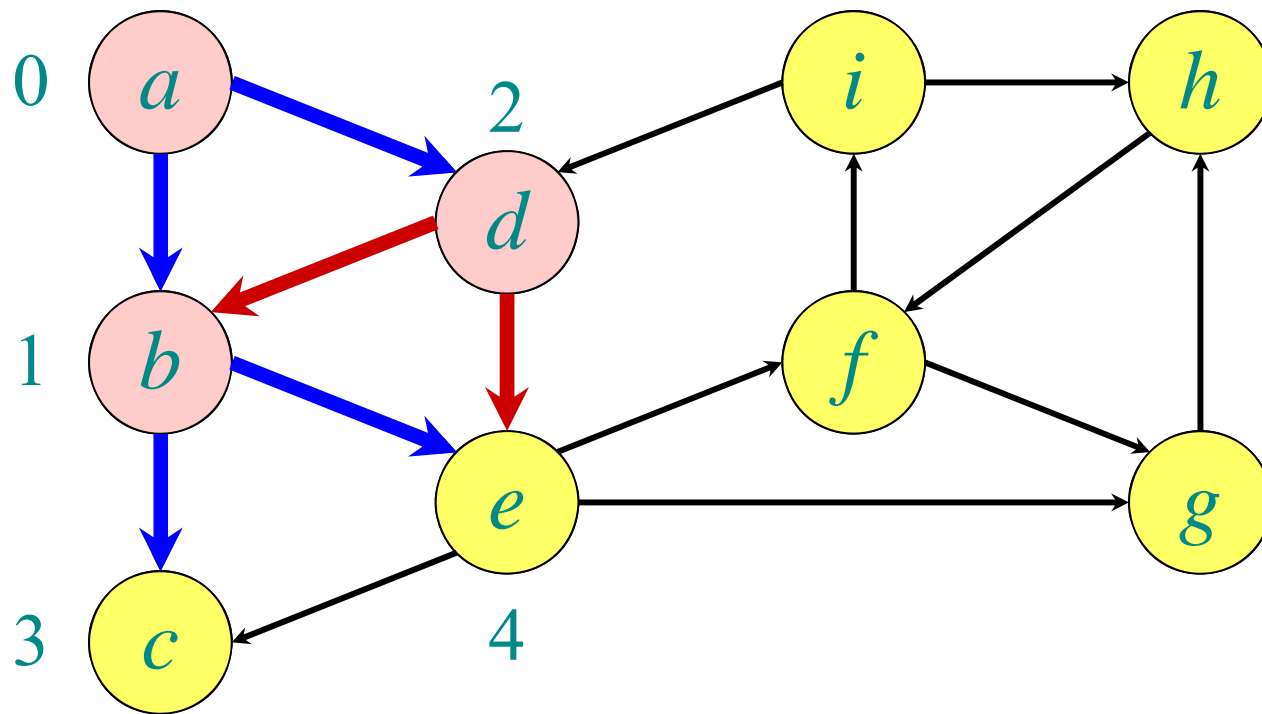
2 3 4

$Q:$   $a$   $b$   $d$   $c$   $e$

$d[v]$  0 1 1 2 2



# Example of breadth-first search

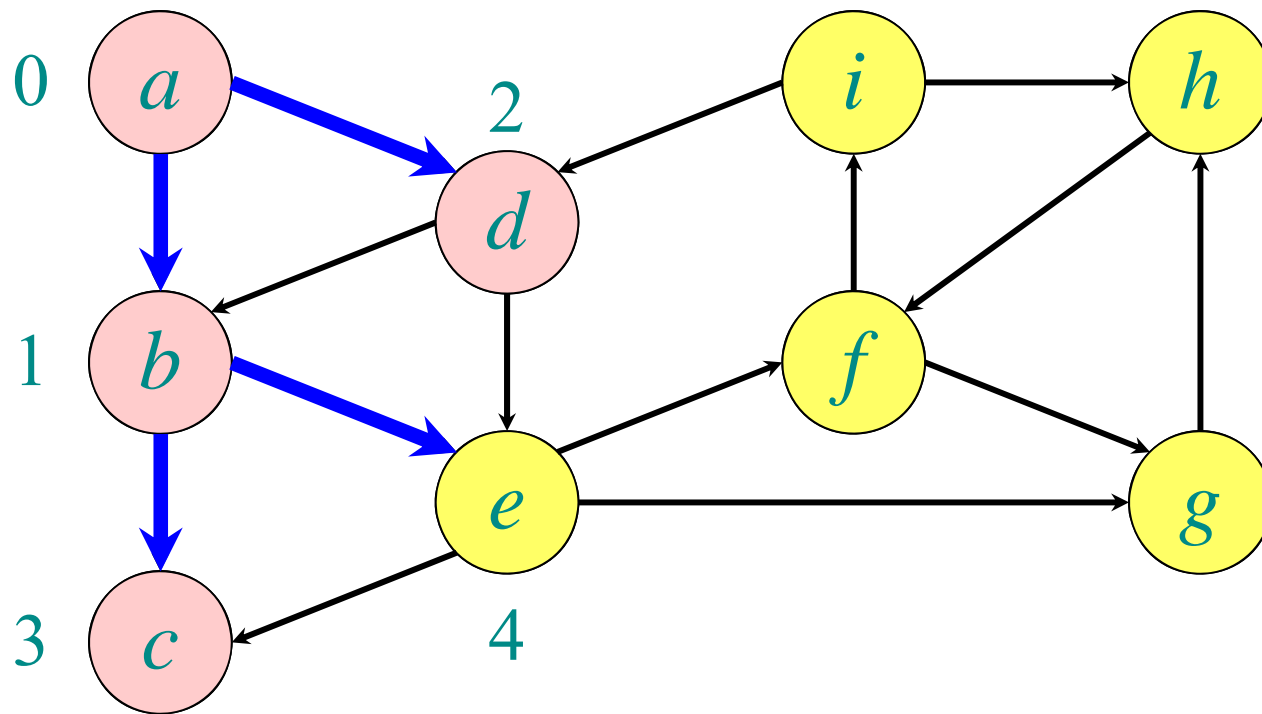


3 4

$Q:$  *a b d c e*

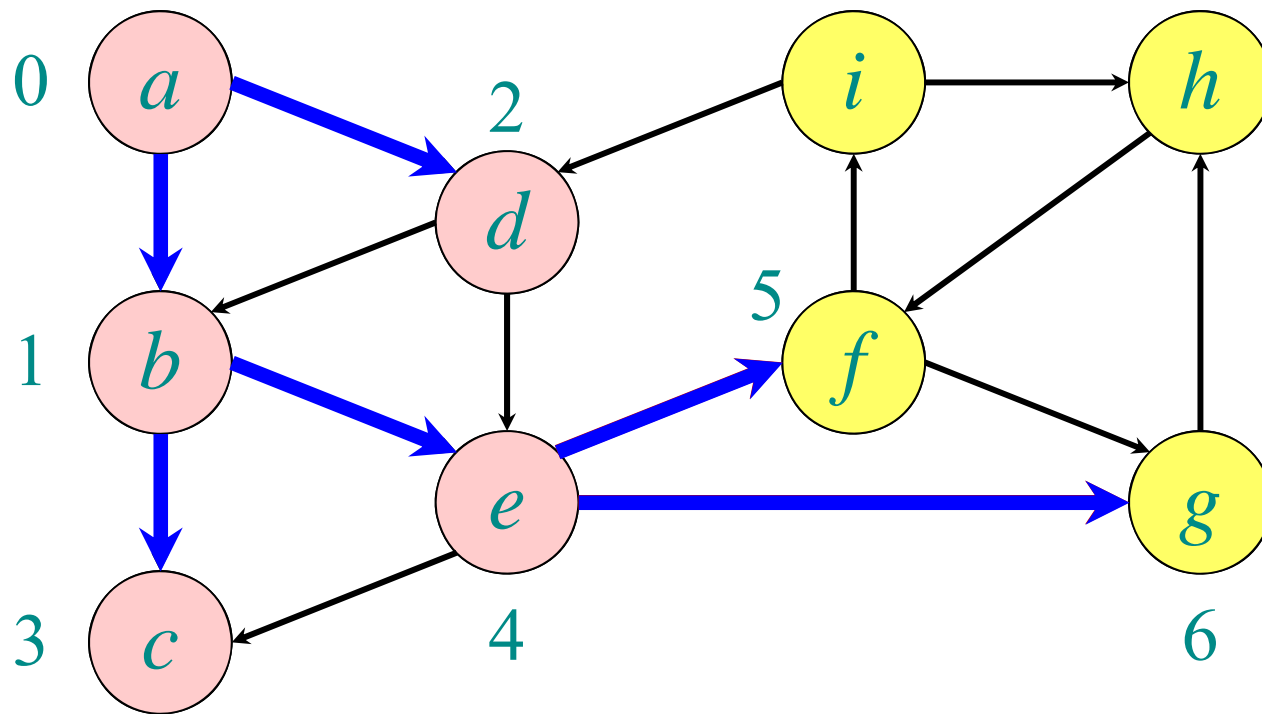
$d[v]$  0 1 1 2 2

# Example of breadth-first search



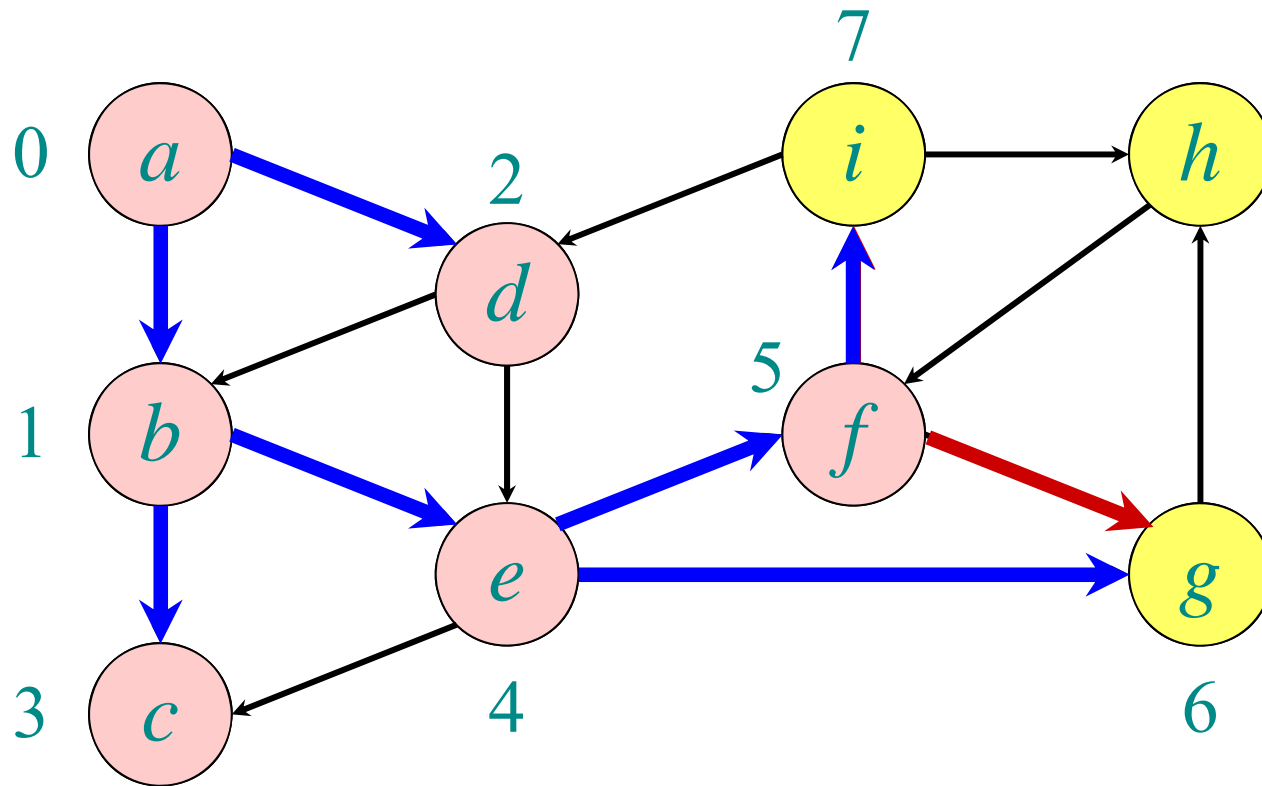
$Q:$  *a b d c e*  
 $d[v]$  *0 1 1 2 2*

# Example of breadth-first search



$Q:$   $a$   $b$   $d$   $c$   $e$   $f$   $g$   
 $d[v]$   $0$   $1$   $1$   $2$   $2$   $3$   $3$

# Example of breadth-first search

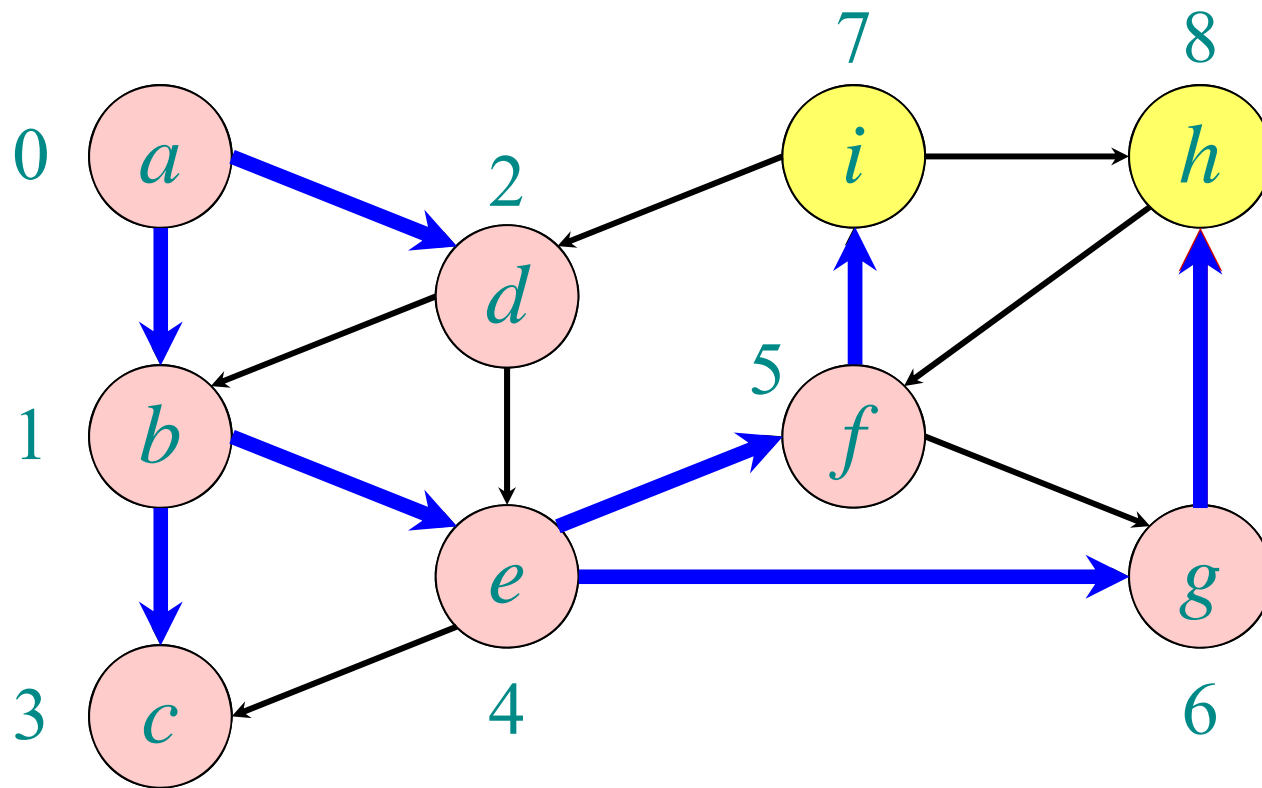


6 7

*Q:* *a b d c e f g i*

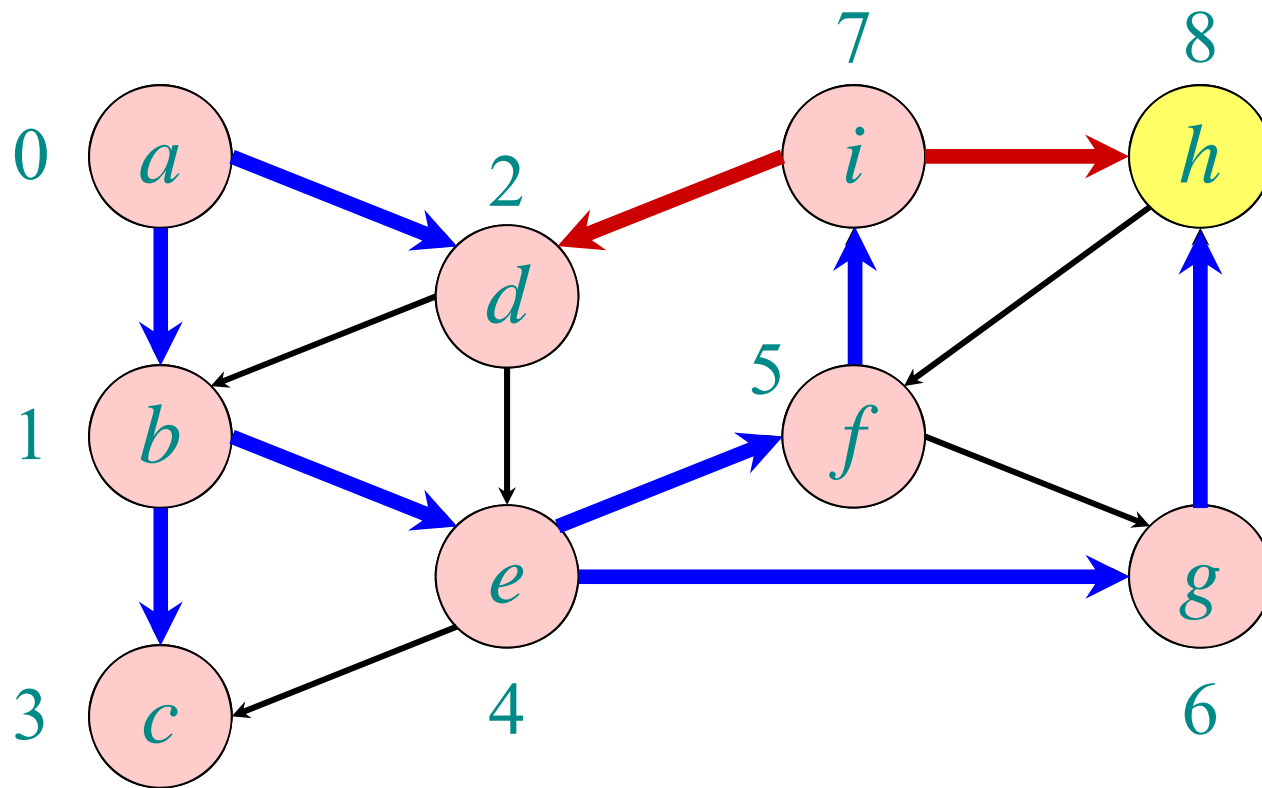
*d[v]* 0 1 1 2 2 3 3 4

# Example of breadth-first search



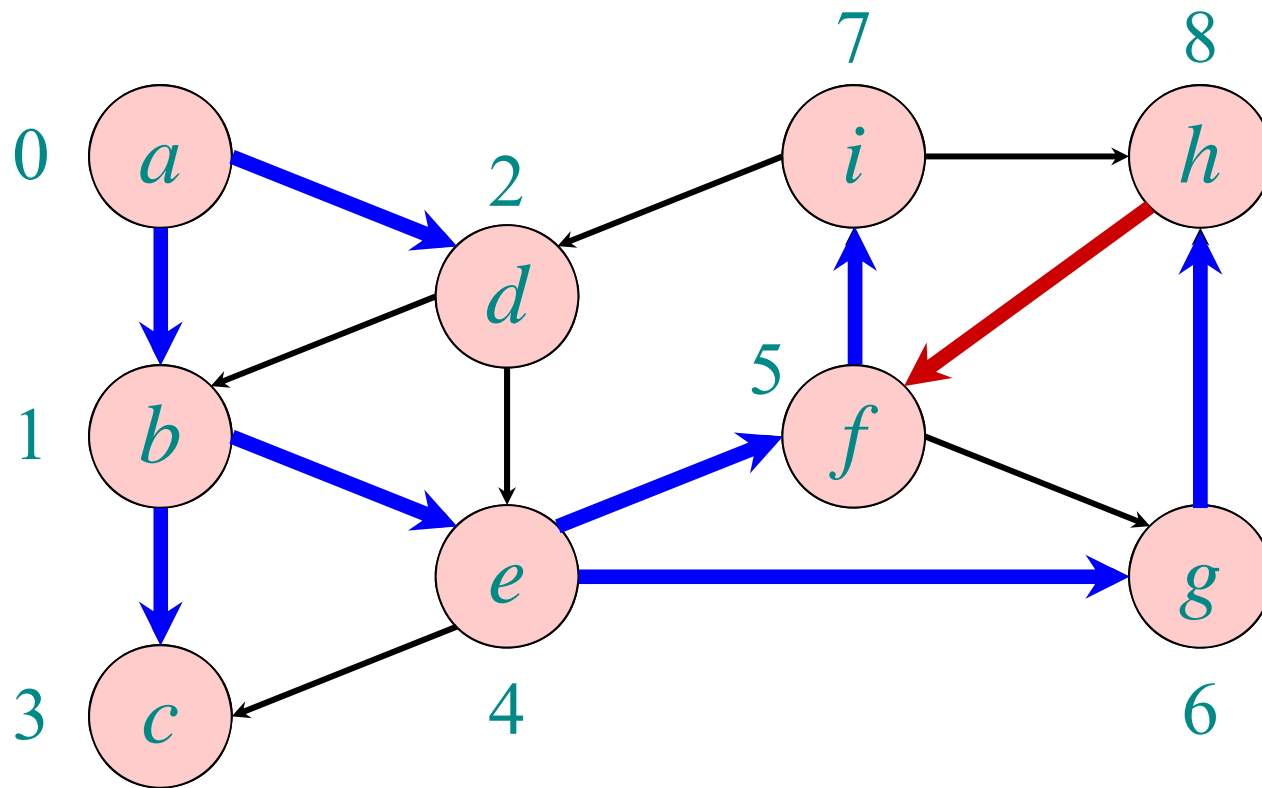
								7	8
$Q:$	$a$	$b$	$d$	$c$	$e$	$f$	$g$	$i$	$h$
$d[v]$	0	1	1	2	2	3	3	4	4

# Example of breadth-first search



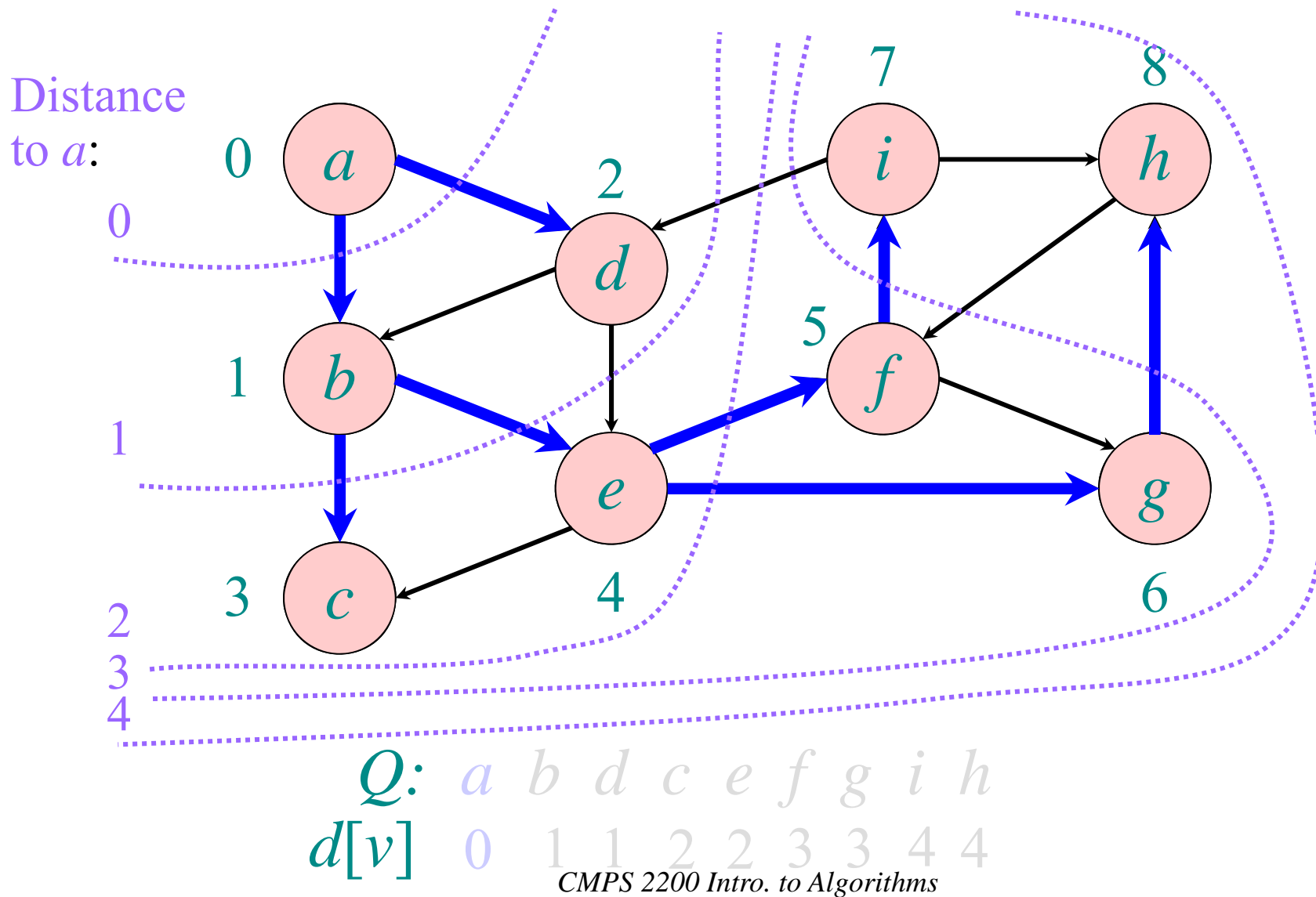
$Q:$   $a$   $b$   $d$   $c$   $e$   $f$   $g$   $i$   $h$   
 $d[v]$   $0$   $1$   $1$   $2$   $2$   $3$   $3$   $4$   $4$

# Example of breadth-first search



$Q:$  *a b d c e f g i h*  
 $d[v]$  *0 1 1 2 2 3 3 4 4*

# Example of breadth-first search





# Correctness of BFS

```
while  $Q \neq \emptyset$  do
   $u \leftarrow Q.\text{DEQUEUE}()$ 
  for each  $v \in \text{Adj}[u]$  do
    if  $d[v] = \infty$  then // unvisited
       $d[v] \leftarrow d[u] + 1$ 
       $Q.\text{ENQUEUE}(v)$ 
```

## Key idea:

The FIFO  $Q$  in breadth-first search mimics the priority queue  $Q$  in Dijkstra.

- **Invariant:**  $v$  comes after  $u$  in  $Q$  implies that  $d[v] = d[u]$  or  $d[v] = d[u] + 1$ .

# How to find the actual shortest paths?

## Store a predecessor tree:

$d[s] \leftarrow 0$

**for each**  $v \in V - \{s\}$  **do**

$d[v] \leftarrow \infty$

$S \leftarrow \emptyset$

$Q \leftarrow V$        $\triangleright$   $Q$  is a priority queue maintaining  $V - S$

**while**  $Q \neq \emptyset$  **do**

$u \leftarrow Q.\text{EXTRACT-MIN}()$

$S \leftarrow S \cup \{u\}$

**for each**  $v \in \text{Adj}[u]$  **do**

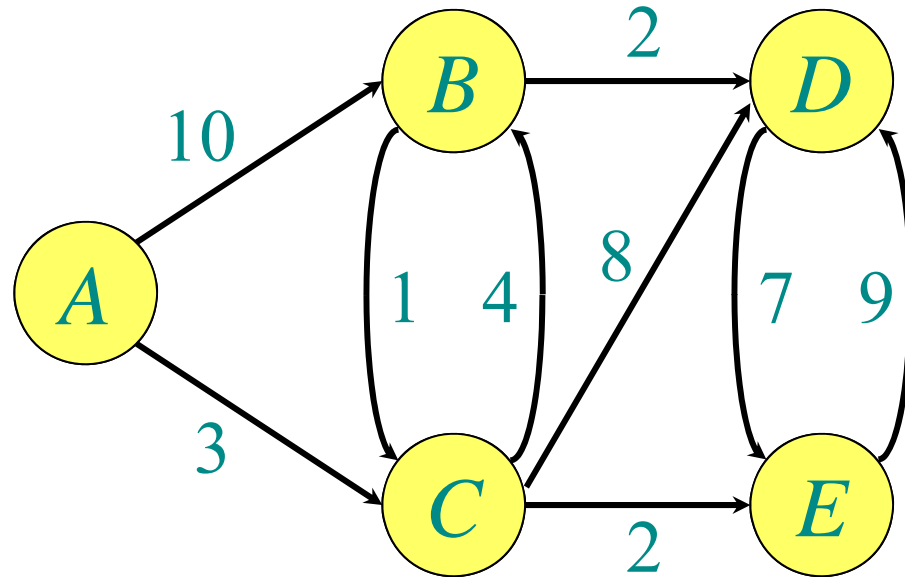
**if**  $d[v] > d[u] + w(u, v)$  **then**

$d[v] \leftarrow d[u] + w(u, v)$

$\pi[v] \leftarrow u$

# Example of Dijkstra's algorithm

Graph with nonnegative edge weights:



```
while  $Q \neq \emptyset$  do
   $u \leftarrow Q.\text{EXTRACT-MIN}()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in \text{Adj}[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
```

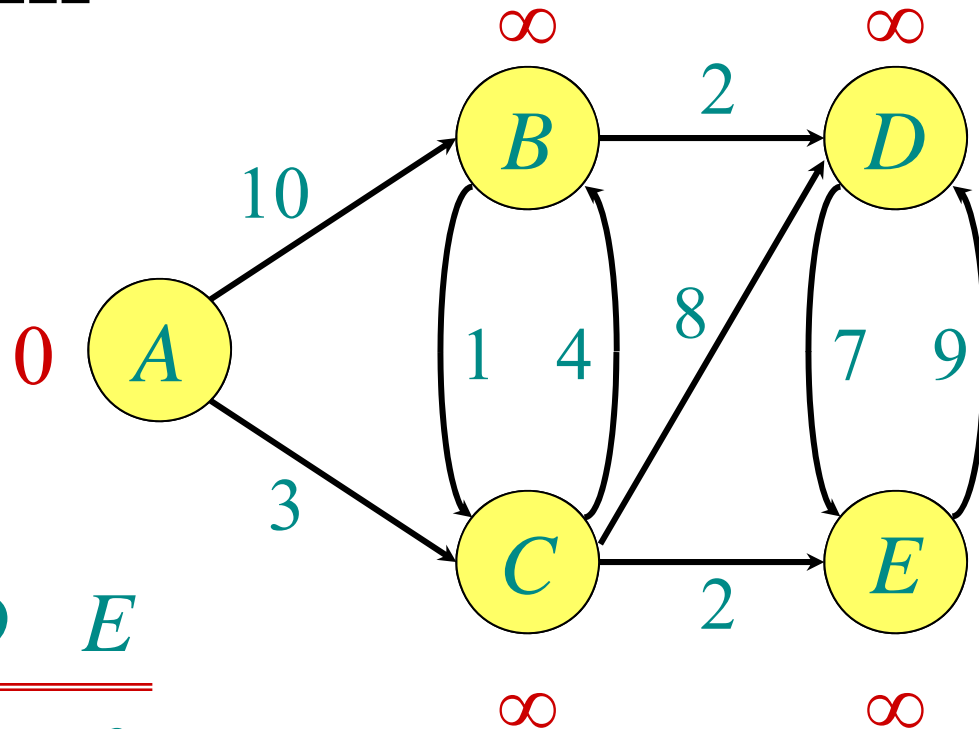
# Example of Dijkstra's algorithm

Initialize:

$S: \{\}$

$Q:$

<u>A</u>	<u>B</u>	<u>C</u>	<u>D</u>	<u>E</u>
0	$\infty$	$\infty$	$\infty$	$\infty$



```
while  $Q \neq \emptyset$  do
   $u \leftarrow Q.\text{EXTRACT-MIN}()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in \text{Adj}[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
```

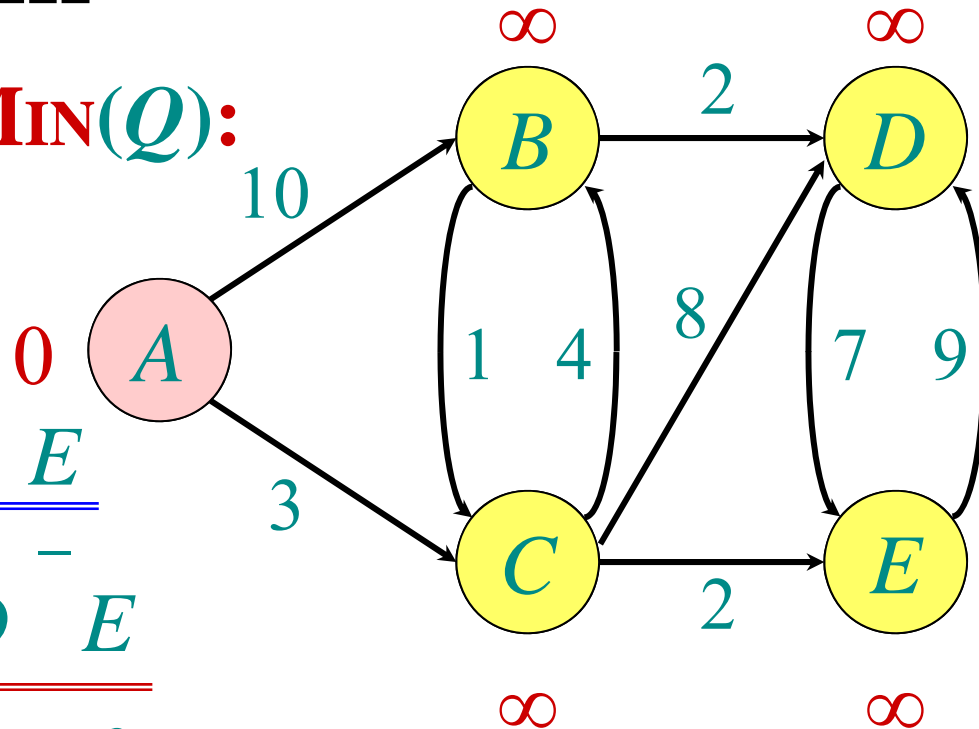
# Example of Dijkstra's algorithm

“A” ← **EXTRACT-MIN**(Q):

S: { A }

$\pi$ : A B C D E

Q: A B C D E  
 0  $\infty$   $\infty$   $\infty$   $\infty$



```

while Q ≠ ∅ do
  u ← Q.EXTRACT-MIN()
  S ← S ∪ {u}
  for each v ∈ Adj[u] do
    if d[v] > d[u] + w(u, v) then
      d[v] ← d[u] + w(u, v)
      π[v] ← u
  
```

# Example of Dijkstra's algorithm

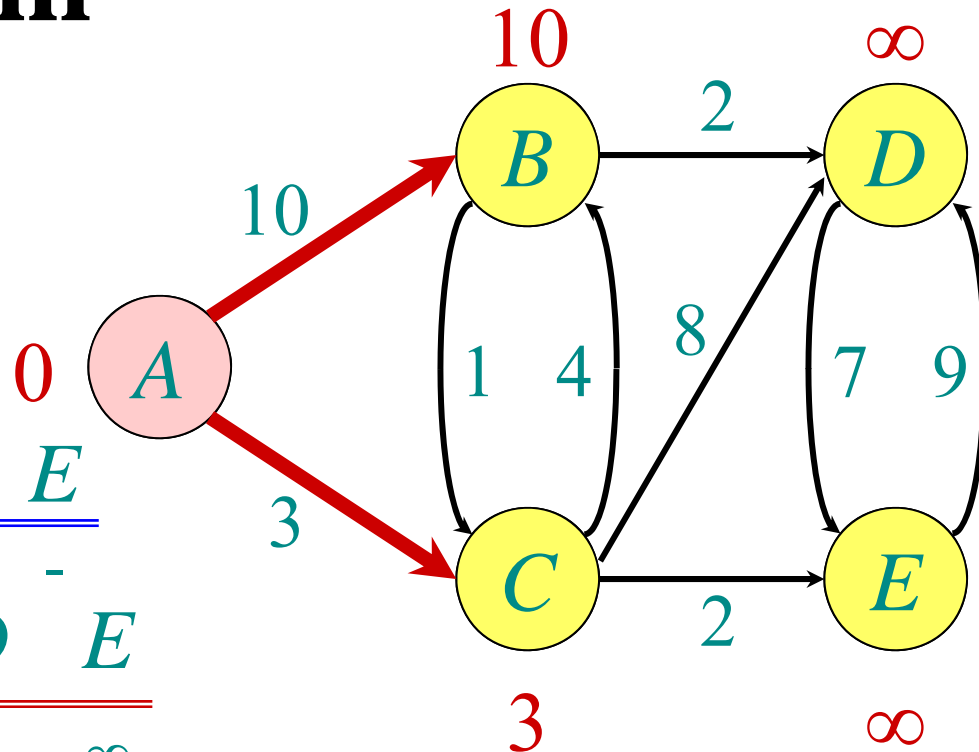
Relax all edges leaving A:

$S: \{A\}$

$\pi: \underline{A \quad B \quad C \quad D \quad E}$

$Q: \underline{A \quad B \quad C \quad D \quad E}$

0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	-	-



```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
  
```

# Example of Dijkstra's algorithm

Relax all edges leaving A:

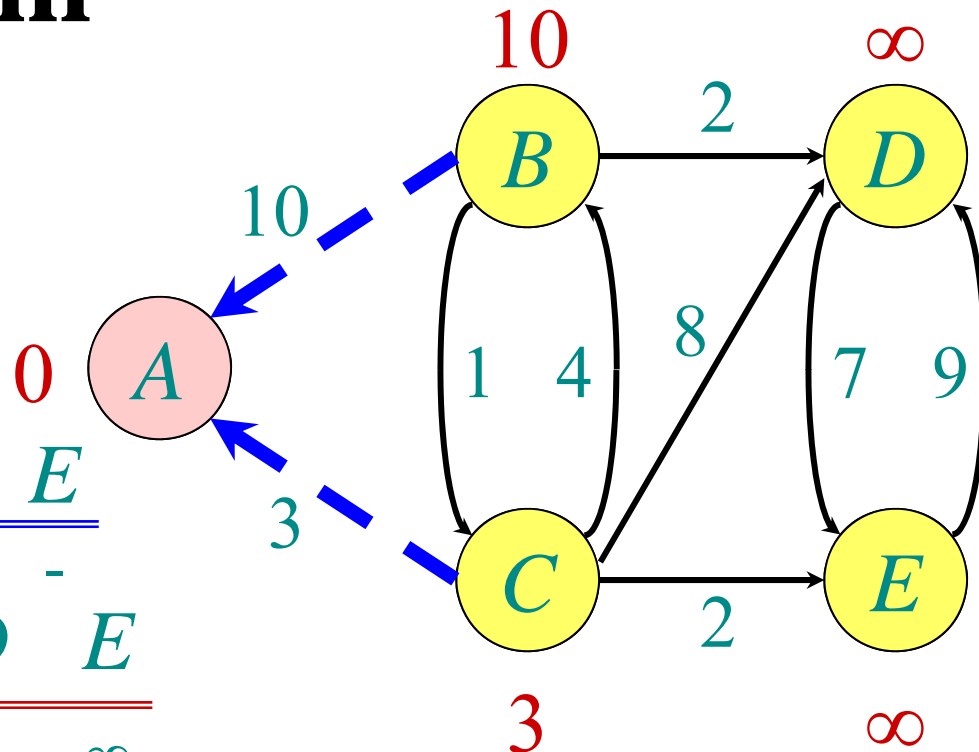
$S: \{A\}$

$\pi:$

A	B	C	D	E
-	A	A	-	-

$Q:$

A	B	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	-	-



```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
  
```

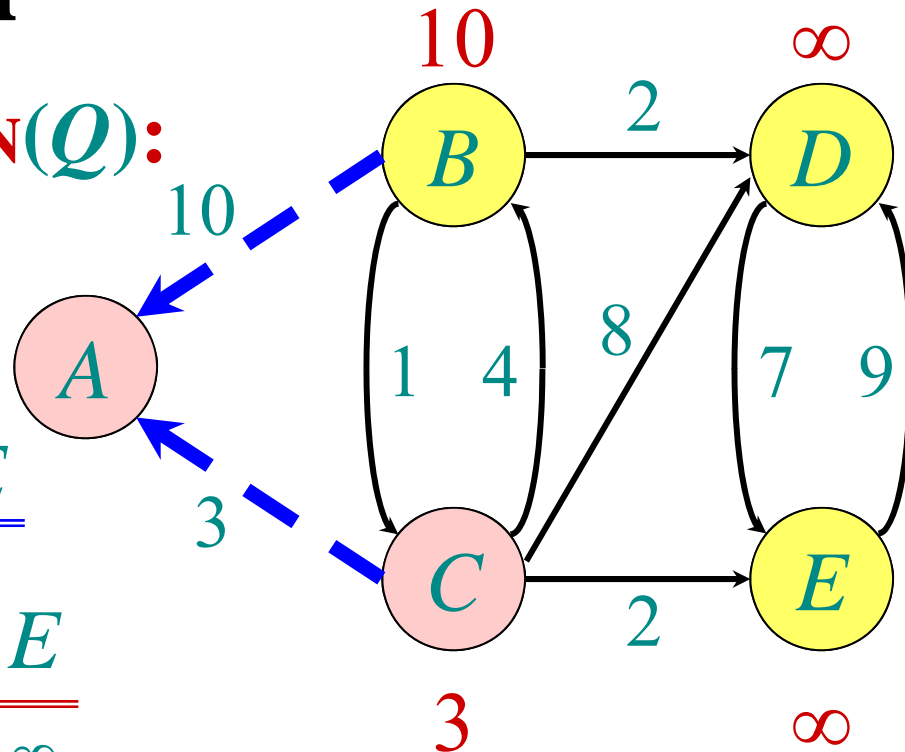
# Example of Dijkstra's algorithm

“C” ← **EXTRACT-MIN(Q)**:

$S: \{A, C\}$

$\pi:$  A B C D E  
 - A A - -

$Q:$	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
		10	3	-	-



```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
  
```



# Example of Dijkstra's algorithm

Relax all edges leaving  $C$ :

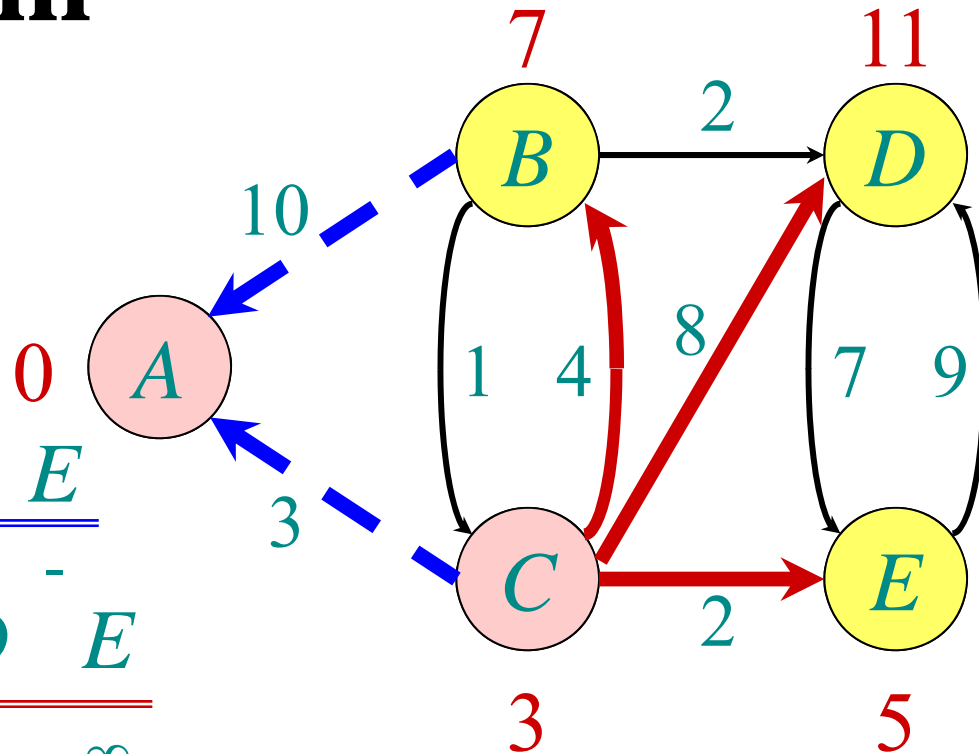
$S: \{A, C\}$

$\pi:$

$A$	$B$	$C$	$D$	$E$
-	$A$	$A$	-	-

$Q:$

$A$	$B$	$C$	$D$	$E$
0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	-	-
	7		11	5



```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
  
```

# Example of Dijkstra's algorithm

Relax all edges leaving  $C$ :

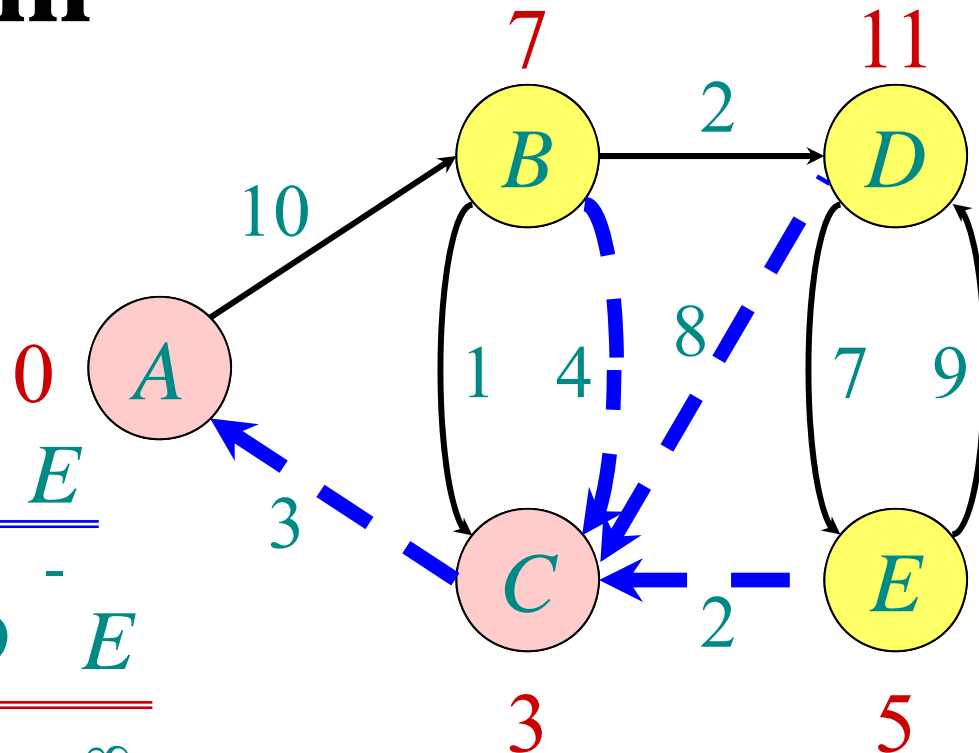
$S: \{A, C\}$

$\pi:$

$A$	$B$	$C$	$D$	$E$
-	$A$	$A$	-	-

$Q:$

$A$	$B$	$C$	$D$	$E$
0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	-	-
	7		11	5



```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
  
```

# Example of Dijkstra's algorithm

“E” ← **EXTRACT-MIN(Q)**:

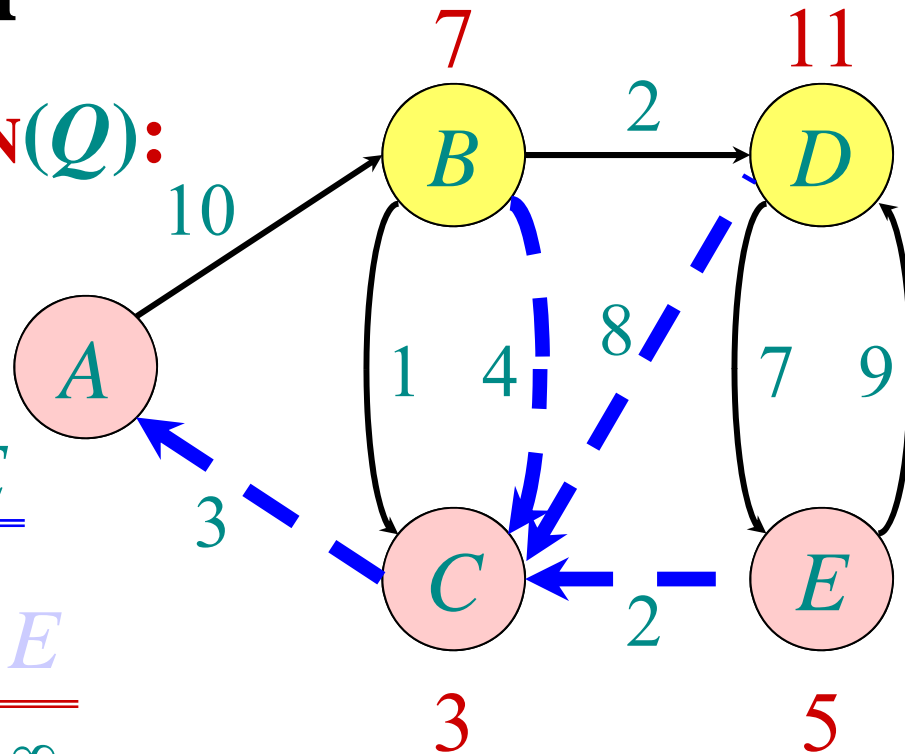
$S: \{A, C, E\}$

$\pi:$

A	B	C	D	E
-	C	A	C	C

$Q:$

A	B	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	-	-
	7		11	5



```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
  
```

# Example of Dijkstra's algorithm

Relax all edges leaving  $E$ :

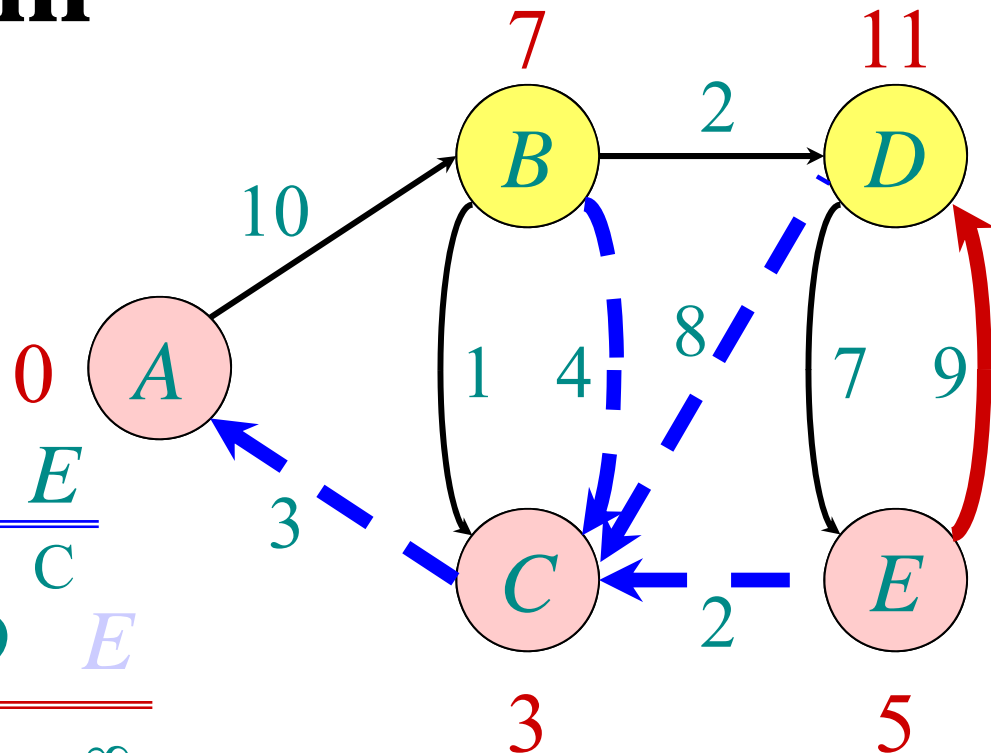
$S: \{A, C, E\}$

$\pi:$

<u>A</u>	<u>B</u>	<u>C</u>	<u>D</u>	<u>E</u>
-	C	A	C	C

$Q:$

A	B	C	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	$\infty$	$\infty$
	7		11	5
	7		11	



```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
  
```

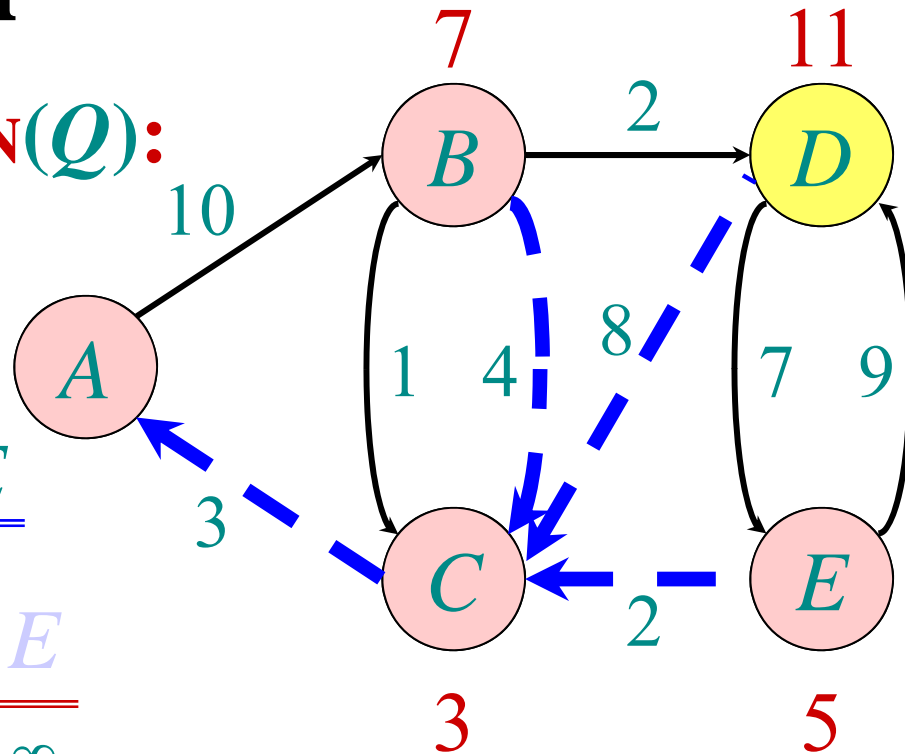
# Example of Dijkstra's algorithm

“B” ← **EXTRACT-MIN**(Q):

S: { A, C, E, B }    0

$\pi$ :     A    B    C    D    E  
       -    C    A    C    C

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
		10	3	$\infty$	$\infty$
		7		11	5
		7		11	



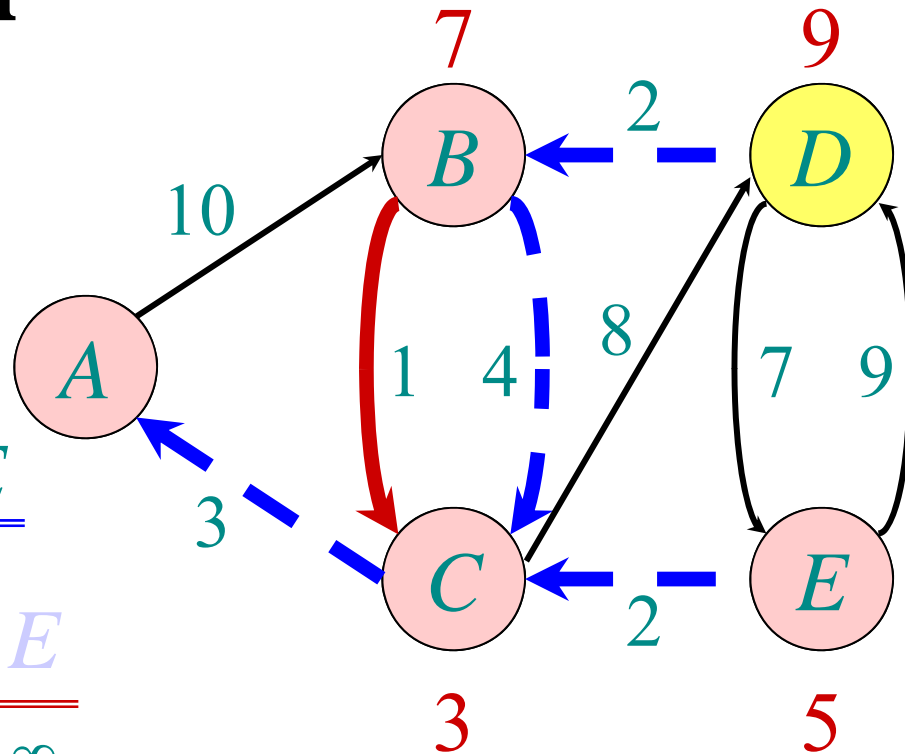
```

while Q ≠ ∅ do
  u ← Q.EXTRACT-MIN()
  S ← S ∪ {u}
  for each v ∈ Adj[u] do
    if d[v] > d[u] + w(u, v) then
      d[v] ← d[u] + w(u, v)
      π[v] ← u
  
```

# Example of Dijkstra's algorithm

Relax all edges leaving  $B$ :

$S: \{A, C, E, B\}$     0  
 $\pi:$     A   B   C   D   E  
           -    C    A    B    C  
 $Q:$     A   B   C   D   E  
           0     $\infty$     $\infty$     $\infty$     $\infty$   
           10    3     $\infty$     $\infty$   
           7       11   5  
           7       11  
           9



```

while  $Q \neq \emptyset$  do
   $u \leftarrow Q.EXTRACT-MIN()$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in Adj[u]$  do
    if  $d[v] > d[u] + w(u, v)$  then
       $d[v] \leftarrow d[u] + w(u, v)$ 
       $\pi[v] \leftarrow u$ 
  
```

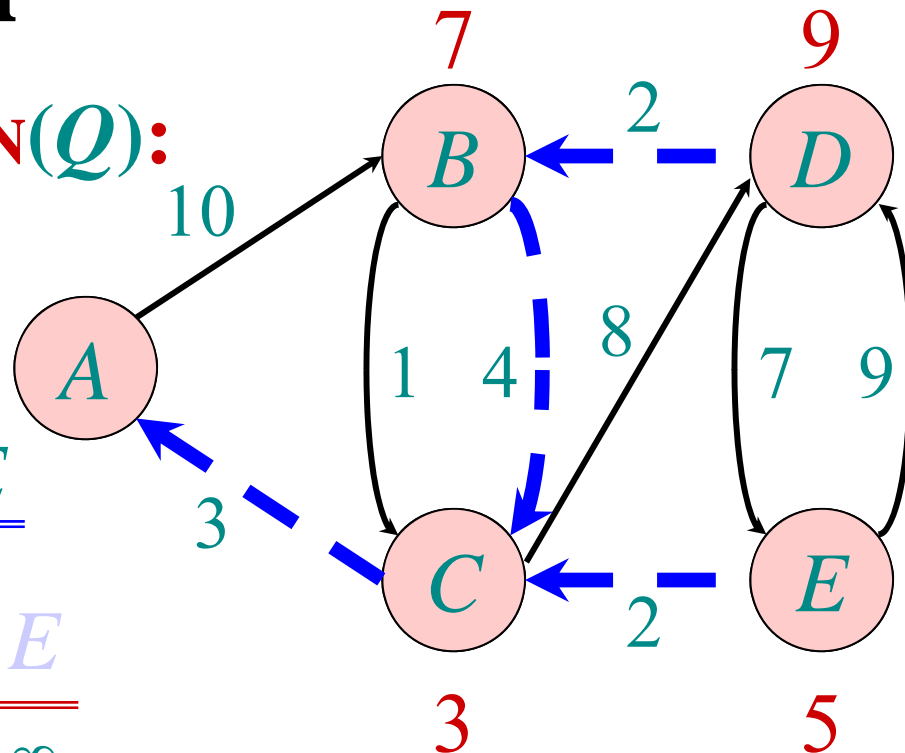
# Example of Dijkstra's algorithm

“D” ← **EXTRACT-MIN**(Q):

S: { A, C, E, B, D } 0

$\pi$ :  A B C D E   
       - C A B C

Q:	A	B	C	D	E
	0	$\infty$	$\infty$	$\infty$	$\infty$
	10	3	$\infty$	$\infty$	$\infty$
	7		11	5	
	7		11		
			9		



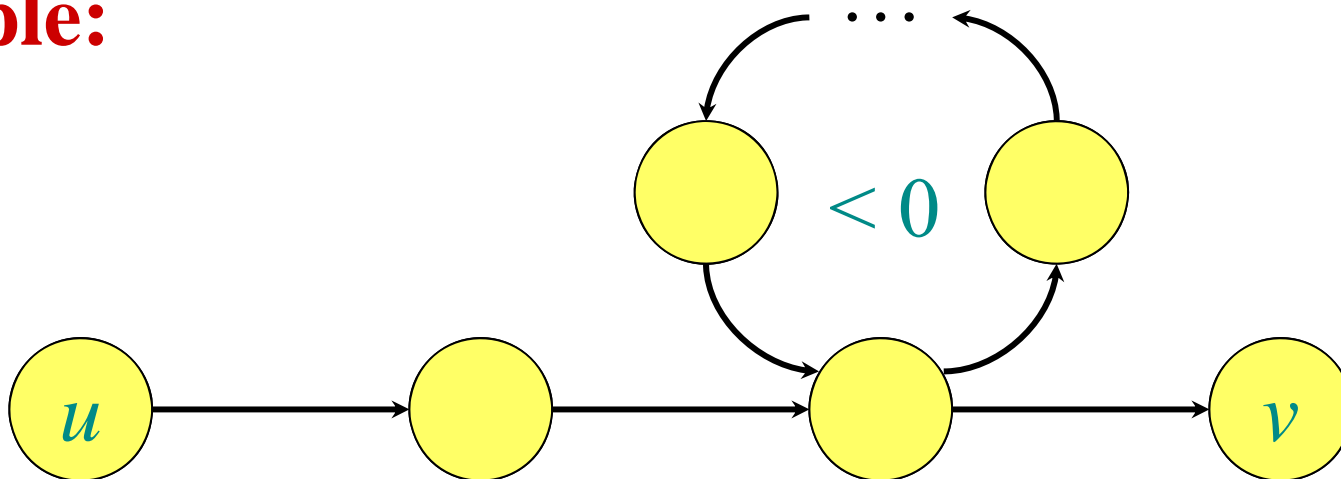
```

while Q ≠ ∅ do
  u ← Q.EXTRACT-MIN()
  S ← S ∪ {u}
  for each v ∈ Adj[u] do
    if d[v] > d[u] + w(u, v) then
      d[v] ← d[u] + w(u, v)
      π[v] ← u
  
```

# Negative-weight cycles

**Recall:** If a graph  $G = (V, E)$  contains a negative-weight cycle, then some shortest paths may not exist.

**Example:**



**Bellman-Ford algorithm:** Finds all shortest-path weights from a **source**  $s \in V$  to all  $v \in V$  or determines that a negative-weight cycle exists.



# Bellman-Ford algorithm

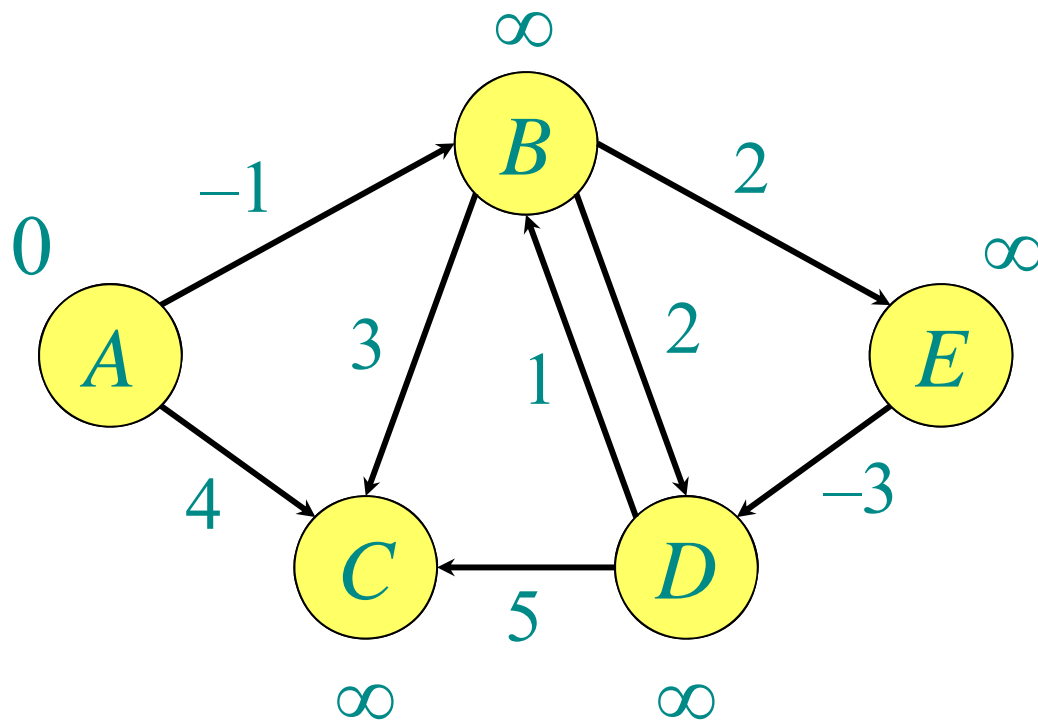
$d[s] \leftarrow 0$   
**for** each  $v \in V - \{s\}$  **do** } initialization  
     $d[v] \leftarrow \infty$

**for**  $i \leftarrow 1$  **to**  $|V| - 1$  **do**  
    **for** each edge  $(u, v) \in E$  **do**  
        **if**  $d[v] > d[u] + w(u, v)$  **then** } *relaxation*  
             $d[v] \leftarrow d[u] + w(u, v)$  } *step*  
             $\pi[v] \leftarrow u$

**for** each edge  $(u, v) \in E$  **do**  
    **if**  $d[v] > d[u] + w(u, v)$   
        **then** report that a negative-weight cycle exists  
At the end,  $d[v] = \delta(s, v)$ . Time =  $O(|V||E|)$ .

# Example of Bellman-Ford

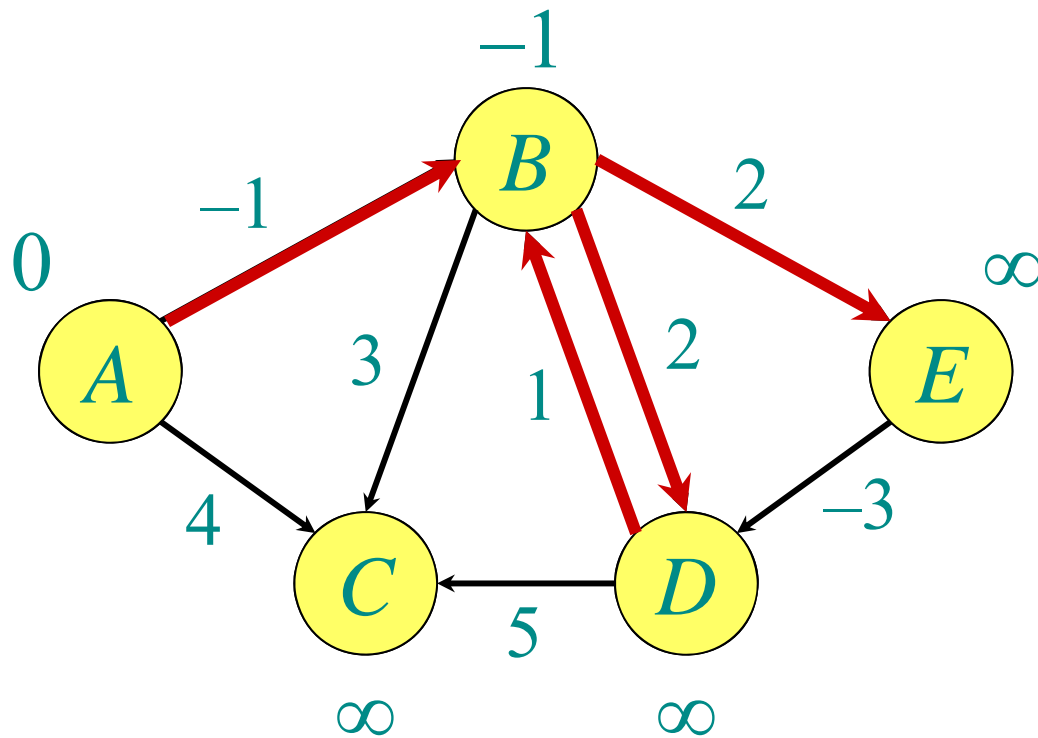
Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$



<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
0	∞	∞	∞	∞

# Example of Bellman-Ford

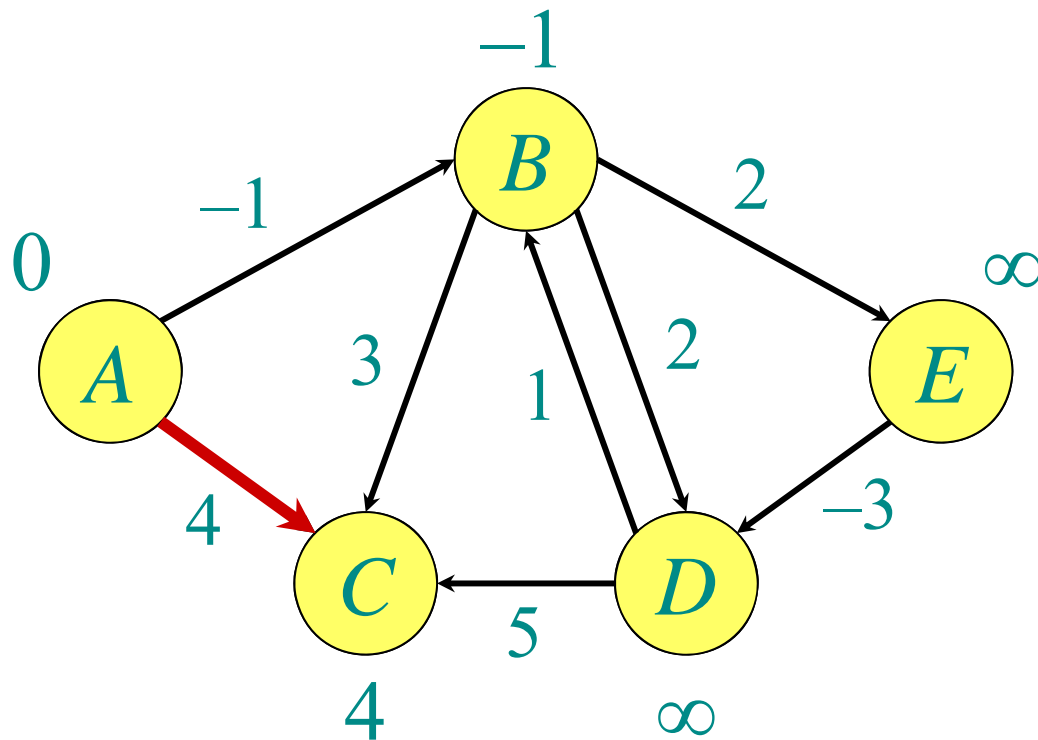
Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$



<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$

# Example of Bellman-Ford

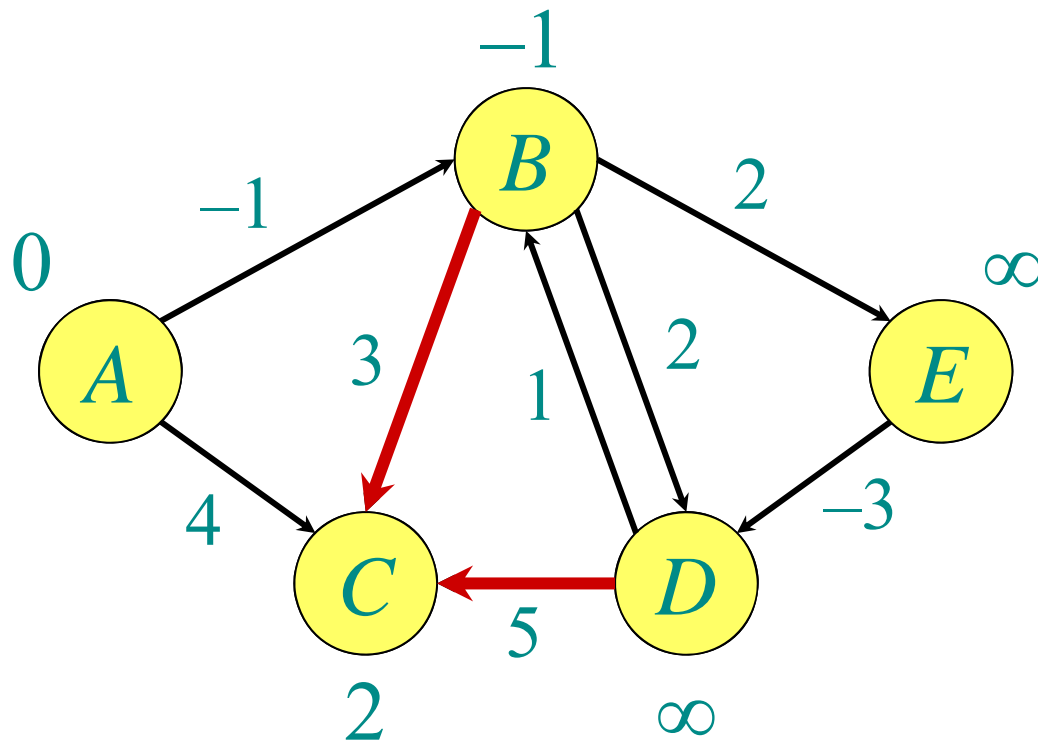
Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$



<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$

# Example of Bellman-Ford

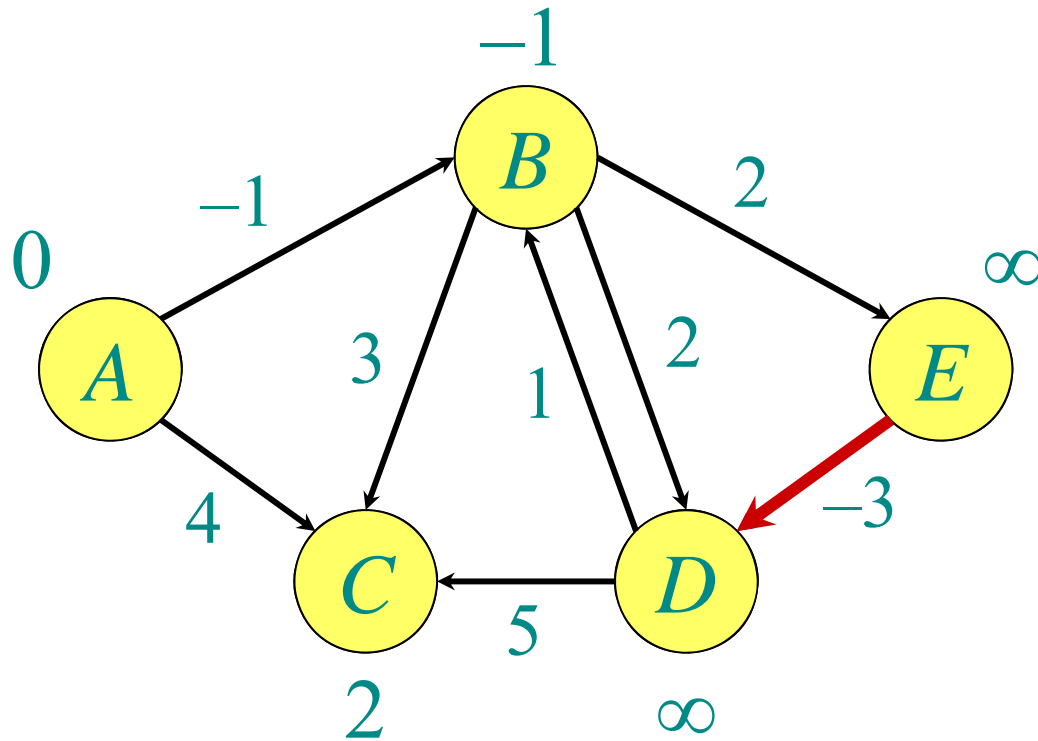
Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$



	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
<i>A</i>	0	$\infty$	$\infty$	$\infty$	$\infty$
<i>B</i>	0	-1	$\infty$	$\infty$	$\infty$
<i>C</i>	0	-1	4	$\infty$	$\infty$
<i>D</i>	0	-1	2	$\infty$	$\infty$

# Example of Bellman-Ford

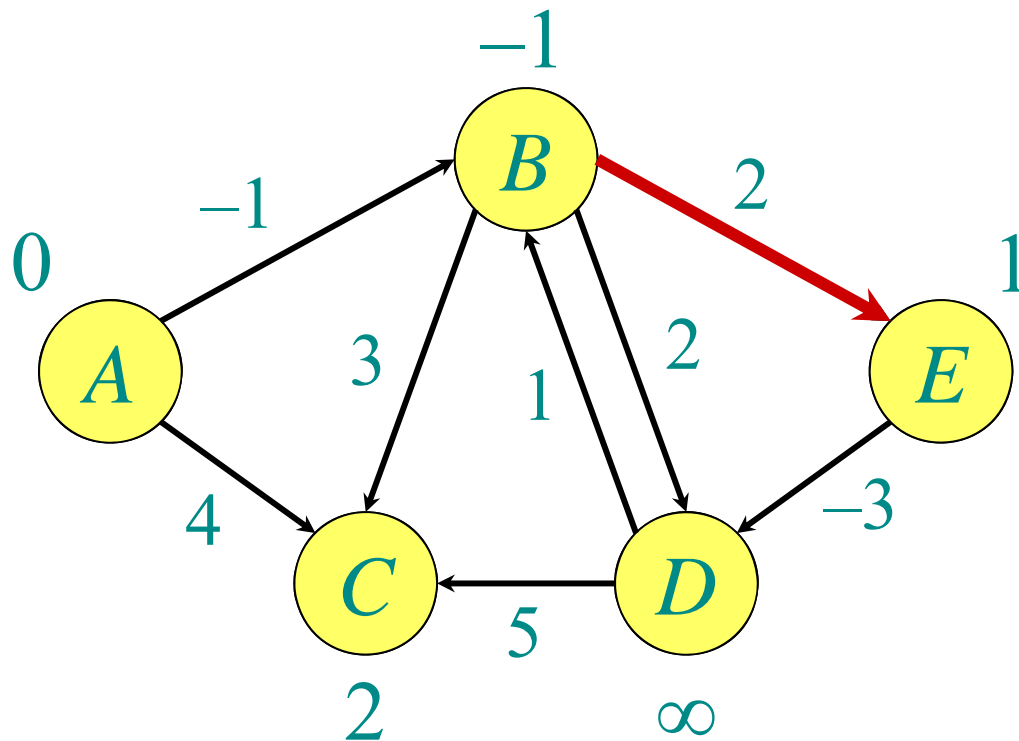
Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$



<u>A</u>	<u>B</u>	<u>C</u>	<u>D</u>	<u>E</u>
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$

# Example of Bellman-Ford

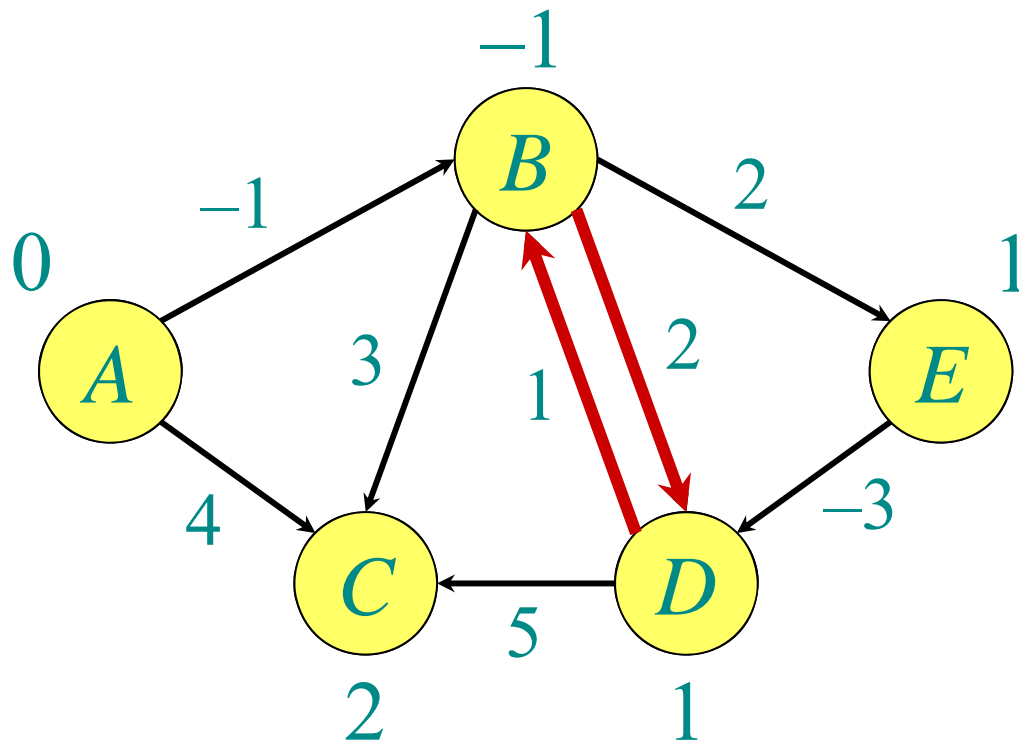
Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$



<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$
0	-1	2	$\infty$	1

# Example of Bellman-Ford

Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$

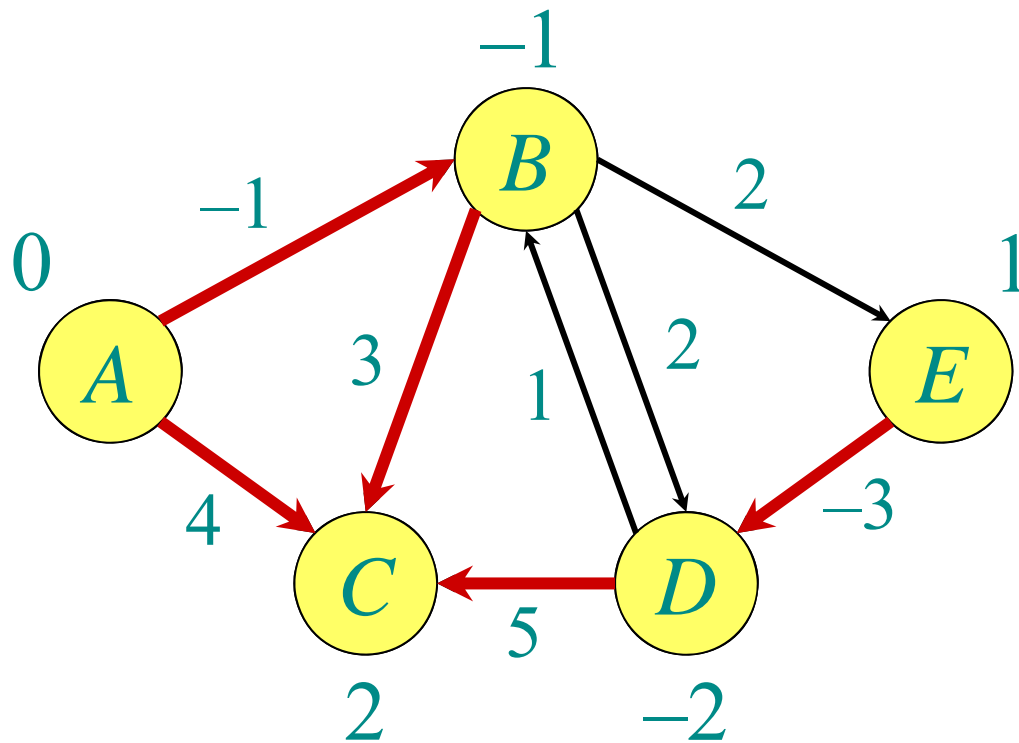


	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
	0	$\infty$	$\infty$	$\infty$	$\infty$
	0	-1	$\infty$	$\infty$	$\infty$
	0	-1	4	$\infty$	$\infty$
	0	-1	2	$\infty$	$\infty$
	0	-1	2	$\infty$	1
	0	-1	2	1	1



# Example of Bellman-Ford

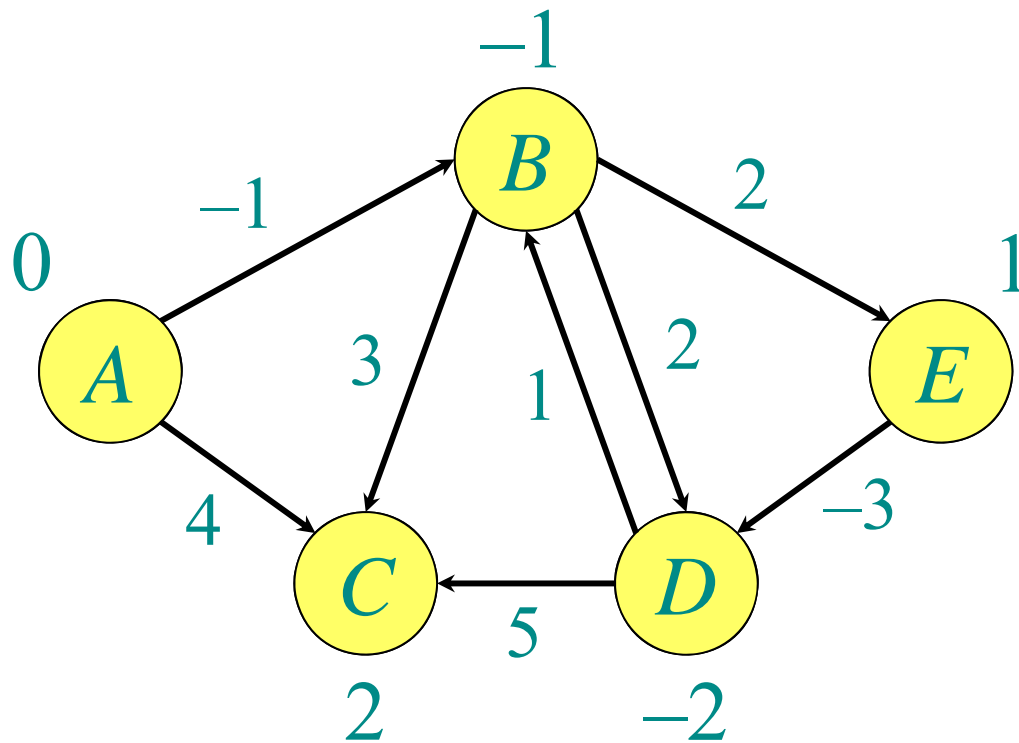
Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$



	<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
	0	$\infty$	$\infty$	$\infty$	$\infty$
	0	-1	$\infty$	$\infty$	$\infty$
	0	-1	4	$\infty$	$\infty$
	0	-1	2	$\infty$	$\infty$
	0	-1	2	$\infty$	1
	0	-1	2	1	1
	0	-1	2	-2	1

# Example of Bellman-Ford

Order of edges:  $(B,E)$ ,  $(D,B)$ ,  $(B,D)$ ,  $(A,B)$ ,  $(A,C)$ ,  $(D,C)$ ,  $(B,C)$ ,  $(E,D)$



**Note:**  $d$ -values decrease monotonically.

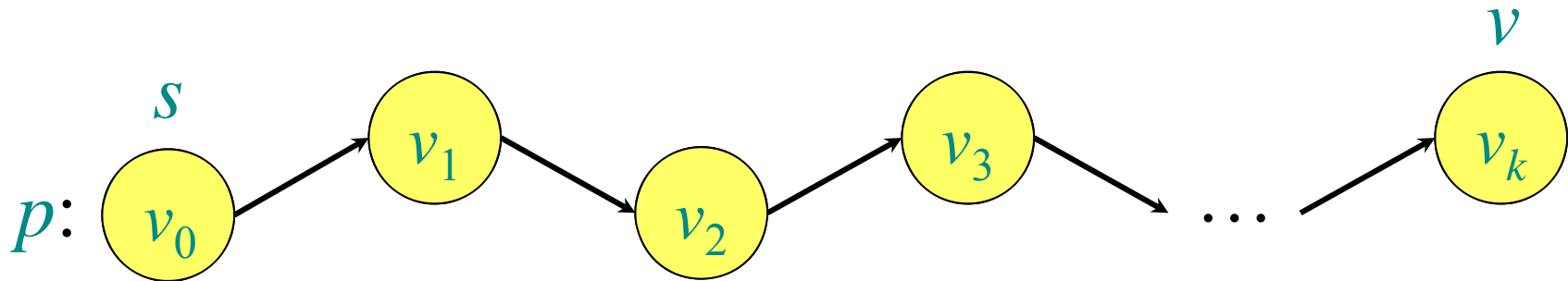
	$A$	$B$	$C$	$D$	$E$
0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$	$\infty$
0	-1	2	$\infty$	1	1
0	-1	2	1	1	1
0	-1	2	-2	1	1

... and 2 more iterations

# Correctness

**Theorem.** If  $G = (V, E)$  contains no negative-weight cycles, then after the Bellman-Ford algorithm executes,  $d[v] = \delta(s, v)$  for all  $v \in V$ .

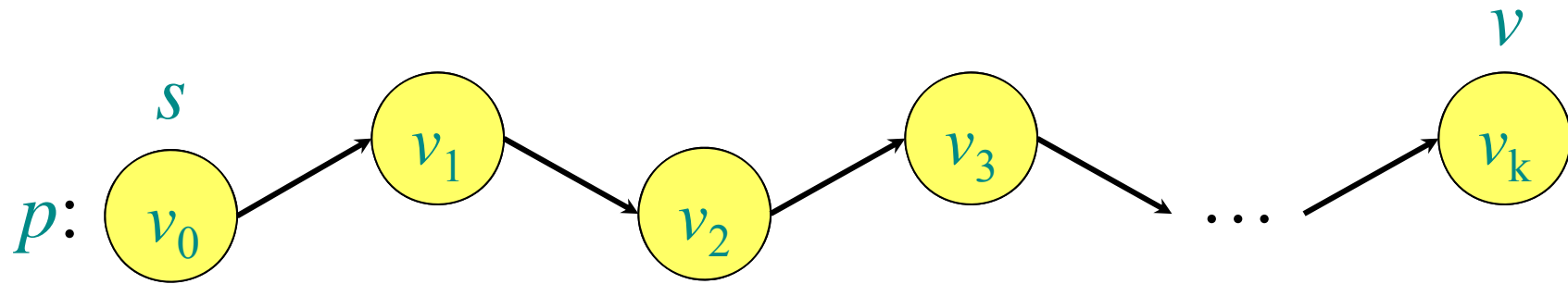
*Proof.* Let  $v \in V$  be any vertex, and consider a shortest path  $p$  from  $s$  to  $v$  with the minimum number of edges.



Since  $p$  is a shortest path, we have

$$\delta(s, v_i) = \delta(s, v_{i-1}) + w(v_{i-1}, v_i) .$$

# Correctness (continued)



Initially,  $d[v_0] = 0 = \delta(s, v_0)$ , and  $d[s]$  is unchanged by subsequent relaxations.

- After 1 pass through  $E$ , we have  $d[v_1] = \delta(s, v_1)$ .
- After 2 passes through  $E$ , we have  $d[v_2] = \delta(s, v_2)$ .
- ...
- After  $k$  passes through  $E$ , we have  $d[v_k] = \delta(s, v_k)$ .

Since  $G$  contains no negative-weight cycles,  $p$  is simple. Longest simple path has  $\leq |V| - 1$  edges.  $\square$

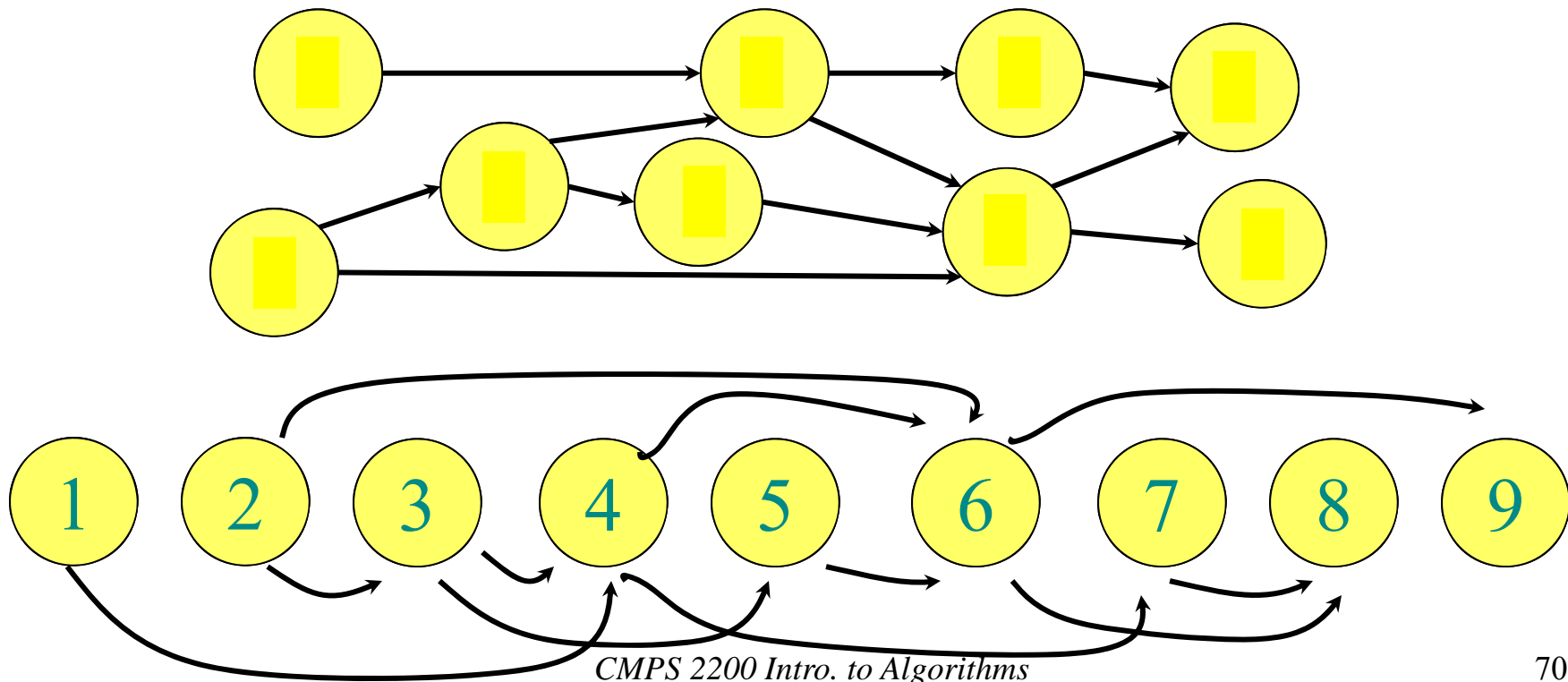
# Detection of negative-weight cycles

**Corollary.** If a value  $d[v]$  fails to converge after  $|V| - 1$  passes, there exists a negative-weight cycle in  $G$  reachable from  $s$ . □

# DAG shortest paths

If the graph is a *directed acyclic graph (DAG)*, we first *topologically sort* the vertices.

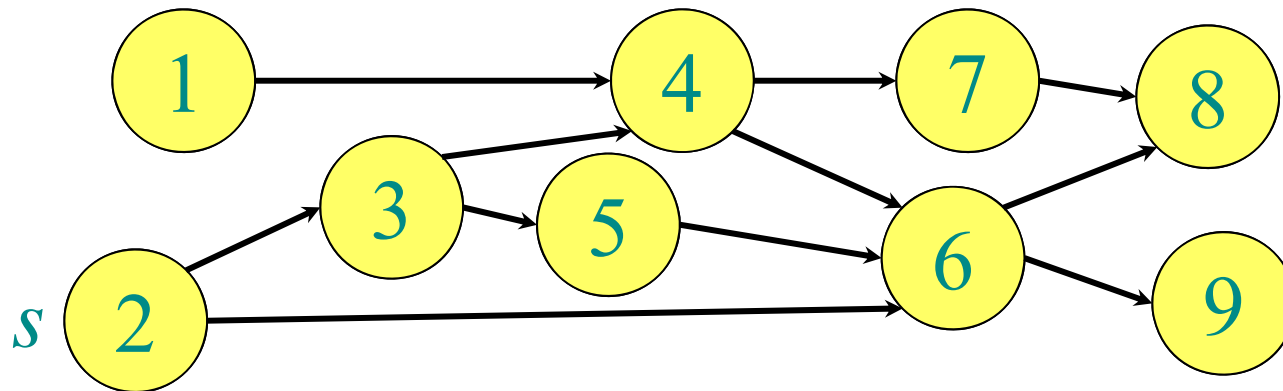
- Determine  $f: V \rightarrow \{1, 2, \dots, |V|\}$  such that  $(u, v) \in E \Rightarrow f(u) < f(v)$ .



# DAG shortest paths

If the graph is a *directed acyclic graph (DAG)*, we first *topologically sort* the vertices.

- Determine  $f: V \rightarrow \{1, 2, \dots, |V|\}$  such that  $(u, v) \in E \Rightarrow f(u) < f(v)$ .
- $O(|V| + |E|)$  time



- Walk through the vertices  $u \in V$  in this order, relaxing the edges in  $Adj[u]$ , thereby obtaining the shortest paths from  $s$  in a total of  $O(|V| + |E|)$  time.

# Shortest paths

## Single-source shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| + |V| \log |V|)$
- General: Bellman-Ford:  $O(|V||E|)$
- DAG: One pass of Bellman-Ford:  $O(|V| + |E|)$

## All-pairs shortest paths



# All-pairs shortest paths

**Input:** Digraph  $G = (V, E)$ , where  $|V| = n$ , with edge-weight function  $w : E \rightarrow \mathbb{R}$ .

**Output:**  $n \times n$  matrix of shortest-path lengths  $\delta(i, j)$  for all  $i, j \in V$ .

## Algorithm #1:

- Run Bellman-Ford once from each vertex.
- Time =  $O(|V|^2 |E|)$ .
- But: Dense graph  $\Rightarrow O(|V|^4)$  time.

# Shortest paths

## Single-source shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| + |V| \log |V|)$
- General: Bellman-Ford:  $O(|V||E|)$
- DAG: One pass of Bellman-Ford:  $O(|V| + |E|)$

## All-pairs shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm  $|V|$  times:  $O(|V||E| + |V|^2 \log |V|)$
- General
  - Bellman-Ford  $|V|$  times:  $O(|V|^2 |E|)$

# Shortest paths

## Single-source shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| + |V| \log |V|)$
- General: Bellman-Ford:  $O(|V||E|)$
- DAG: One pass of Bellman-Ford:  $O(|V| + |E|)$

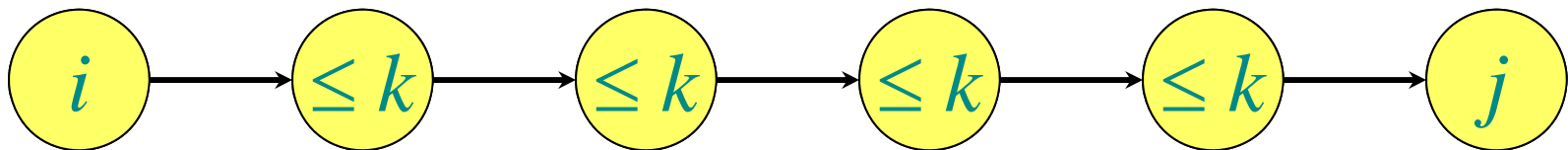
## All-pairs shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm  $|V|$  times:  $O(|V||E| + |V|^2 \log |V|)$
- General
  - Bellman-Ford  $|V|$  times:  $O(|V|^2 |E|)$
  - Floyd-Warshall:  $O(|V|^3)$

# Floyd-Warshall algorithm

- Dynamic programming algorithm.
- Assume  $V = \{1, 2, \dots, n\}$ , and assume  $G$  is given in an **adjacency matrix**  $A = (a_{ij})_{1 \leq i, j \leq n}$  where  $a_{ij}$  is the weight of the edge from  $i$  to  $j$ .

Define  $c_{ij}^{(k)}$  = weight of a shortest path from  $i$  to  $j$  with intermediate vertices belonging to the set  $\{1, 2, \dots, k\}$ .



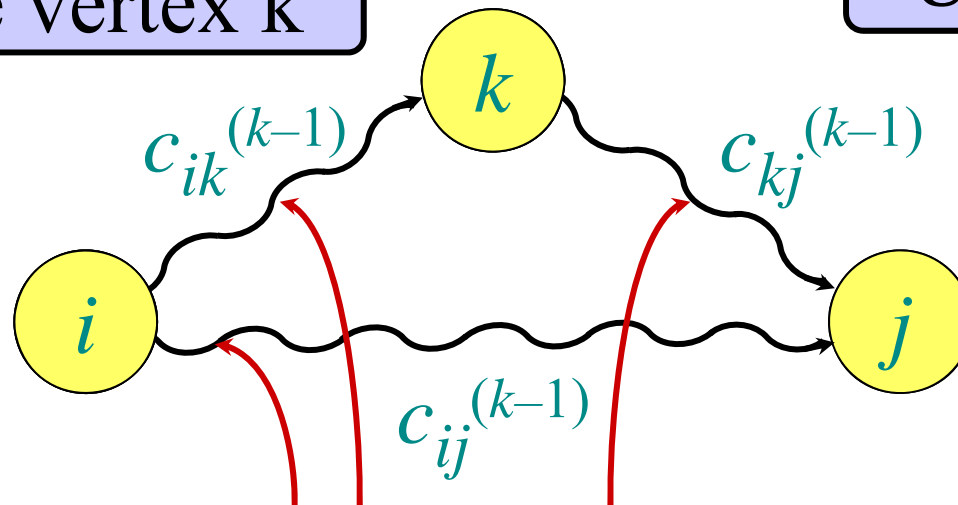
Thus,  $\delta(i, j) = c_{ij}^{(n)}$ . Also,  $c_{ij}^{(0)} = a_{ij}$ .

# Floyd-Warshall recurrence

$$c_{ij}^{(k)} = \min \{c_{ij}^{(k-1)}, c_{ik}^{(k-1)} + c_{kj}^{(k-1)}\}$$

Do not use vertex k

Use vertex k



intermediate vertices in  $\{1, 2, \dots, k-1\}$

# Pseudocode for Floyd-Warshall

```
for  $k \leftarrow 1$  to  $n$  do
  for  $i \leftarrow 1$  to  $n$  do
    for  $j \leftarrow 1$  to  $n$  do
      if  $c_{ij}^{(k-1)} > c_{ik}^{(k-1)} + c_{kj}^{(k-1)}$  then
         $c_{ij}^{(k)} \leftarrow c_{ik}^{(k-1)} + c_{kj}^{(k-1)}$ 
      else
         $c_{ij}^{(k)} \leftarrow c_{ij}^{(k-1)}$ 
```

} *relaxation*

- Runs in  $\Theta(n^3)$  time and space
- Simple to code.
- Efficient in practice.

# Transitive Closure of a Directed Graph

Compute  $t_{ij} = \begin{cases} 1 & \text{if there exists a path from } i \text{ to } j, \\ 0 & \text{otherwise.} \end{cases}$

**IDEA:** Use Floyd-Warshall, but with  $(\vee, \wedge)$  instead of  $(\min, +)$ :

$$t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee (t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)}).$$

Time =  $\Theta(n^3)$ .

**Floyd-Warshall recurrence**

$$c_{ij}^{(k)} = \min \{c_{ij}^{(k-1)}, c_{ik}^{(k-1)} + c_{kj}^{(k-1)}\}$$

# Shortest paths

## Single-source shortest paths

- Nonnegative edge weights
    - Dijkstra's algorithm:  $O(|E| + |V| \log |V|)$
  - General: Bellman-Ford:  $O(|V||E|)$
  - DAG: One pass of Bellman-Ford:  $O(|V| + |E|)$
- } adj. list

## All-pairs shortest paths

- Nonnegative edge weights
    - Dijkstra's algorithm  $|V|$  times:  $O(|V||E| + |V|^2 \log |V|)$
  - General
    - Bellman-Ford  $|V|$  times:  $O(|V|^2 |E|)$
    - Floyd-Warshall:  $O(|V|^3)$
- adj. list  
adj. list  
adj. matrix