CMPS 2200 – Fall 2017

Dynamic Programming II Carola Wenk

Slides courtesy of Charles Leiserson with changes and additions by Carola Wenk

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CMPS 2200 Intro. to Algorithms

Dynamic programming

- Algorithm design technique
- A technique for solving problems that have
 - 1. an optimal substructure property (recursion)
 - 2. overlapping subproblems
- Idea: Do not repeatedly solve the same subproblems, but solve them only once and store the solutions in a dynamic programming table

Longest Common Subsequence

Example: Longest Common Subsequence (LCS) • Given two sequences $x[1 \dots m]$ and $y[1 \dots n]$, find a longest subsequence common to them both. "a" not "the" functional notation, but not a function

Brute-force LCS algorithm

Check every subsequence of $x[1 \dots m]$ to see if it is also a subsequence of $y[1 \dots n]$.

Analysis

- 2^m subsequences of x (each bit-vector of length m determines a distinct subsequence of x).
- Hence, the runtime would be exponential !

Towards a better algorithm

Two-Step Approach:

- 1. Look at the *length* of a longest-common subsequence.
- 2. Extend the algorithm to find the LCS itself.

Notation: Denote the length of a sequence s by |s|.

Strategy: Consider *prefixes* of *x* and *y*.

- Define c[i, j] = |LCS(x[1 ... i], y[1 ... j])|.
- Then, c[m, n] = |LCS(x, y)|.

Recursive formulation

Let z[1 ldots k] = LCS(x[1 ldots i], y[1 ldots j]), where c[i, j]= k. Then, z[k] = x[i], or else z could be extended. Thus, z[1 ldots k-1] is CS of x[1 ldots i-1] and y[1 ldots j-1].

Proof (continued)

Claim: z[1 ... k-1] = LCS(x[1 ... i-1], y[1 ... j-1]). Suppose w is a longer CS of x[1 ... i-1] and y[1 ... j-1], that is, |w| > k-1. Then, cut and paste: $w \parallel z[k]$ (w concatenated with z[k]) is a common subsequence of x[1 ... i] and y[1 ... j] with $|w| \parallel z[k] \mid > k$. Contradiction, proving the claim.

Thus, c[i-1, j-1] = k-1, which implies that c[i, j] = c[i-1, j-1] + 1.

Other cases are similar.

Dynamic-programming hallmark #1

Optimal substructure An optimal solution to a problem (instance) contains optimal solutions to subproblems.

Recursion

If z = LCS(x, y), then any prefix of z is an LCS of a prefix of x and a prefix of y.

Recursive algorithm for LCS

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LCS(x, y, i, j)

if (i=0 or j=0)

c[i, j] \leftarrow 0

else if x[i] = y[j]

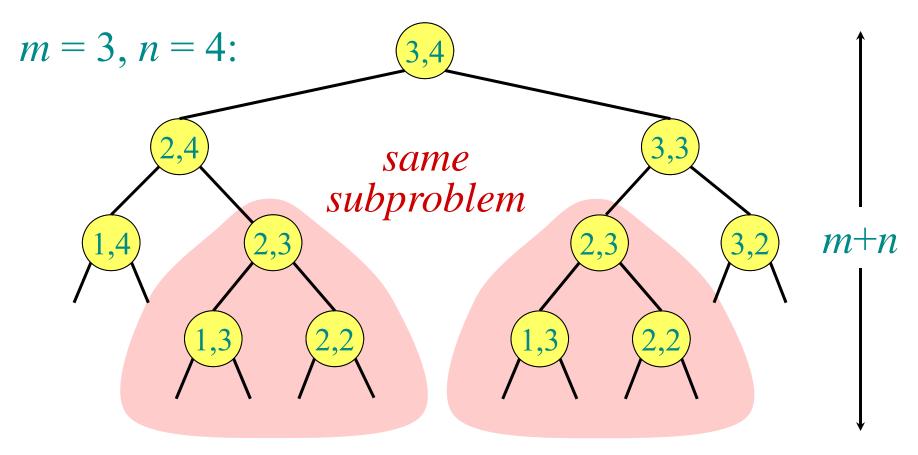
c[i, j] \leftarrow LCS(x, y, i-1, j-1) + 1

else c[i, j] \leftarrow max \{LCS(x, y, i-1, j), LCS(x, y, i, j-1)\}

return c[i, j]
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Worst-case: $x[i] \neq y[j]$, in which case the algorithm evaluates two subproblems, each with only one parameter decremented.

Recursion tree (worst case)



Height = $m + n \Rightarrow$ work potentially exponential, but we're solving subproblems already solved!

Dynamic-programming hallmark #2

Overlapping subproblems A recursive solution contains a "small" number of distinct subproblems repeated many times.

The distinct LCS subproblems are all the pairs (i,j). The number of such pairs for two strings of lengths m and n is only mn.

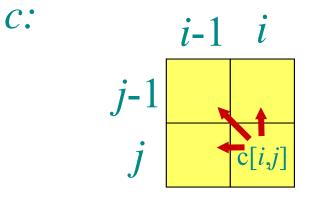
Memoization algorithm

Memoization: After computing a solution to a subproblem, store it in a table. Subsequent calls check the table to avoid redoing work.

LCS mem(x, y, i, j)if c[i, j] = null**if** (*i*=0 or *j*=0) $c[i, j] \leftarrow 0$ same else if x[i] = y[j]as $c[i, j] \leftarrow \text{LCS} \text{mem}(x, y, i-1, j-1) + 1$ before else $c[i, j] \leftarrow \max\{LCS \mod (x, y, i-1, j), \}$ LCS mem (x, y, i, j-1)return c[i, j] Space = time = $\Theta(mn)$; constant work per table entry. 10/11/17CMPS 2200 Intro. to Algorithms

Recursive formulation

$$c[i, j] = \begin{cases} c[i-1, j-1] + 1 & \text{if } x[i] = y[j], \\ \max\{c[i-1, j], c[i, j-1]\} & \text{otherwise.} \end{cases}$$



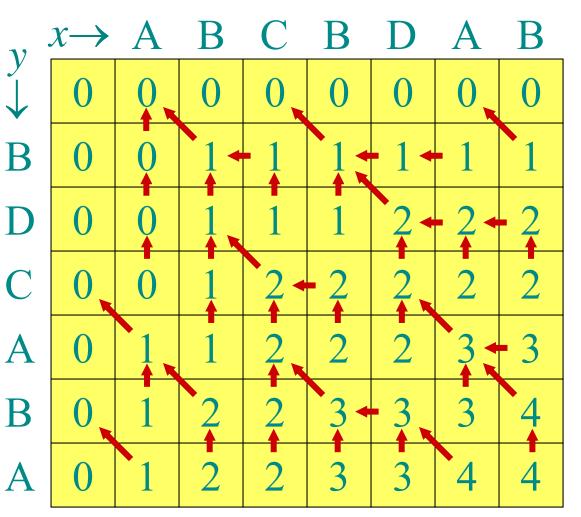
$i-1 \quad i$ j-1 j c[i,j]

Bottom-up dynamicprogramming algorithm

IDEA:

Compute the table bottom-up.

Time = $\Theta(mn)$.



Bottom-up DP

Space = time = $\Theta(mn)$; constant work per table entry.

LCS bottomUp(x[1..m], y[1..n]) for $(i=0; i\le m; i++) c[i,0]=0;$ for $(j=0; j\le n; j++) c[0,j]=0;$ for $(j=1; j \le n; j++)$ for $(i=1; i \le m; i++)$ **if** x[i] = y[j] { $c[i, j] \leftarrow c[i-1, j-1]+1$ arrow[i,j]="diagonal"; } else { // compute max **if** $(c[i-1, j] \ge c[i, j-1])$ { $c[i, j] \leftarrow c[i-1, j]$ arrow[i,j]="left"; } else{ $c[i, j] \leftarrow c[i, j-1]$ arrow[i,j]="right"; } return c and arrow

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$i-1 \quad i$ j-1 j c[i,j]

Bottom-up dynamicprogramming algorithm

IDEA:

Compute the table bottom-up.

Time = $\Theta(mn)$.

Reconstruct LCS by backtracking.

Space = $\Theta(mn)$. Exercise: $O(\min\{m, n\})$.

